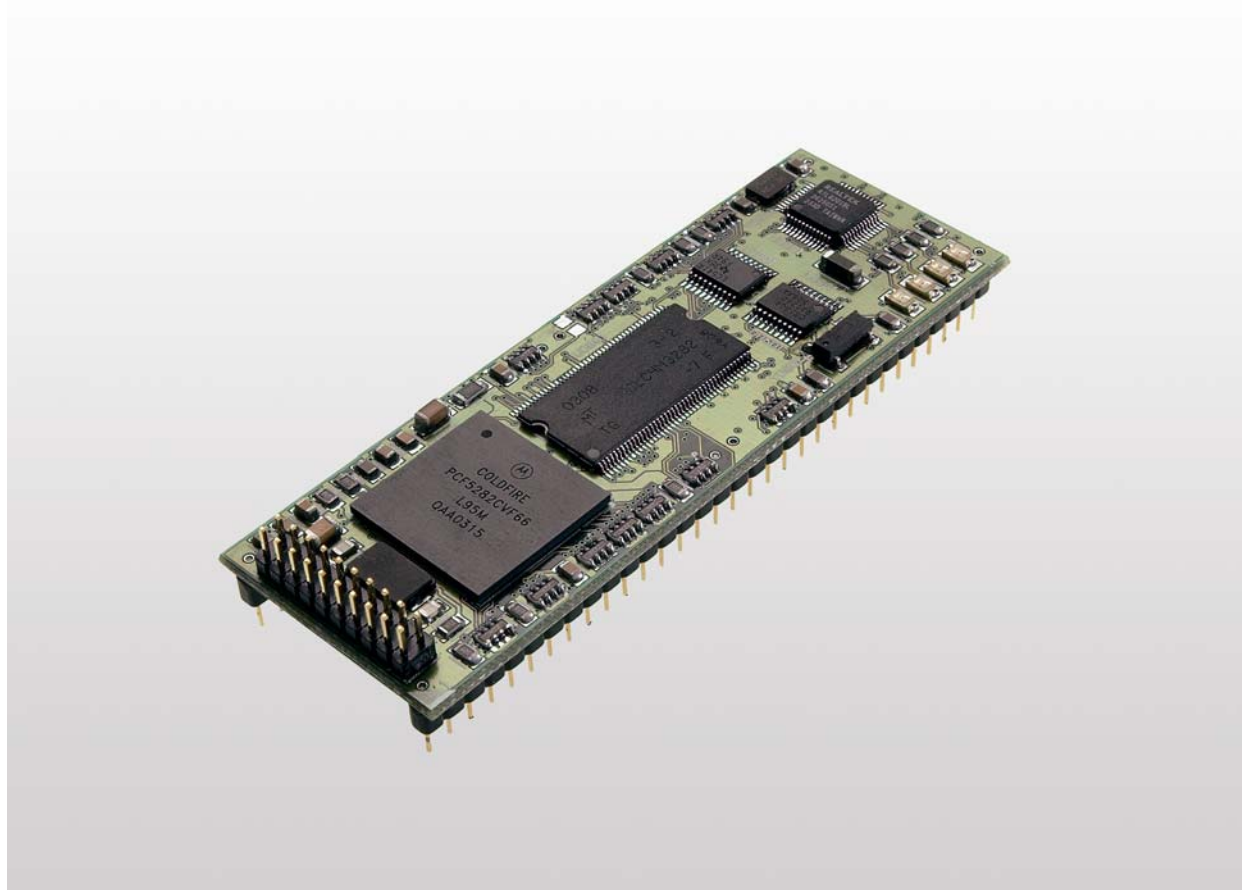


DIL/NetPC DNP/5280 ***Starter Kit***

User Manual



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1 Introduction

Thank you for choosing an SSV Starter Kit. We are confident that you will be pleased with the performance of your product. Please take a few minutes to read this manual. It describes how to start with the DNP/SK13 Starter Kit and will help you to get out the most of your new system.

For further information about the individual components of this Starter Kit you may follow the links from our website at: <http://www.dilnetpc.com>

Our Website contains a lot of technical information, which will be updated in regular periods.

For specific technical information – like hardware description etc. – please check out the Starter Kit CD-ROM, which is an important part of every Starter Kit.

1.1 Conventions used in this Document

Convention	Usage
<i>italic</i>	Filenames, Internet addresses like e.g. www.ssv-embedded.de
<i>bold italic</i>	User inputs, command lines and pathnames
bold	New terms
monospace	Program code
E	Keyboard button

Table 1-1: Convention usage

1.2 Checklist

Compare the content of your Starter Kit package with the checklist below. If any item is missing or appears to be damaged, please contact SSV Embedded Systems.

Standard Items

- ✓ Evaluation Board DNP/EVA2-SV6
- ✓ DIL/NetPC DNP/5280
- ✓ Null-Modem cable
- ✓ Power Supply
- ✓ Power Cable
- ✓ User Manual
- ✓ Support CD-ROM

1.3 Features

Evaluation Board DNP/EVA2-SV6

- 64-pin DIL socket for one DIL/NetPC DNP/5280
- One Serial Interface, 1 x RS232
- 10/100Mbps Ethernet Interface
- Eight User-Definable LEDs
- Eight Manual DIP Switches
- One Reset Switch
- Prototype-Area
- 5 VDC Power Input Connector
- Size 140 x 120 mm

DIL/NetPC DNP/5280

- Motorola 32-bit MCF5280 ColdFire with 66 MHz Clock Speed
- 63 MIPS (Dhrystone 2.1)
- 16 MByte SDRAM Memory, 8 MByte FLASH Memory
- 10/100 Mbps Ethernet LAN Interface
- Four LAN Status LEDs
- Two asynchronous Serial Ports (one with all Handshakes)
- One I2C Interchip Bus Interface
- One Queued Serial Peripheral Interface (SPI)
- One CAN Interface (Supports CAN Protocol Specification 2.0B)
- 20-bit General Purpose high-speed Parallel I/O
- 8-bit I/O Expansion Bus
- Five Interrupt Inputs
- Four Chip Select Outputs
- Programmable General Purpose Timers and Watchdog Timer
- Motorola BDM (Background Debug Mode) Interface for In-Circuit Debugging
- In-System Programming Features
- 64-pin JEDEC DIL-64 Connector, 2.54mm Centers
- 3.3 Volt Low Power Design, Supply Voltage 3.3 VDC (+- 5%)
- Supply Current 300 mA typ. at 66 MHz
- Size 82mm * 28mm

2 Board Layout

The main component of the Starter Kit is the Evaluation Board DNP/EVA2-SV6. On this board you will find a 64-pin DIL socket (DIL = Dual In Line) to mount your DNP/5280.

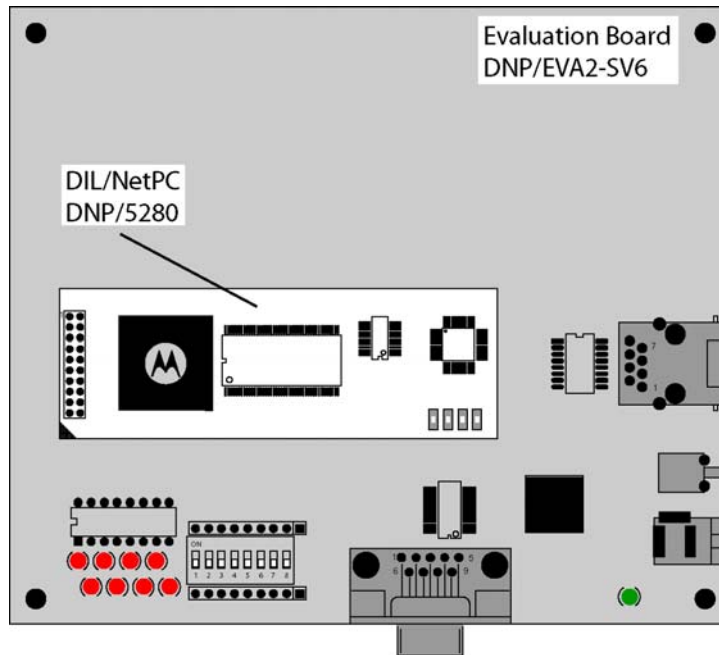


Figure 2-1: Evaluation Board EVA2 with DNP/5280

The Starter Kit DNP/SK13 provides all required basic hard- and software environment, which allows you the development of individual applications for your DNP/5280.

For an instant connection to your hardware the Evaluation Board supports a serial COM interface, a 10/100Mbps Ethernet interface as well as a DIL-64 interface. Further you will find a prototype (wire-wrap) area, eight LEDs, DIP-switches and one reset switch, which allows you to test your peripheral applications very easy. With the prototype area you have a good place to install and to test your own applications on the Evaluation Board.

3 Board Components

This chapter describes the most interesting components of the Evaluation Board DNP/EVA2-SV6 and gives a short overview about their respective functions.

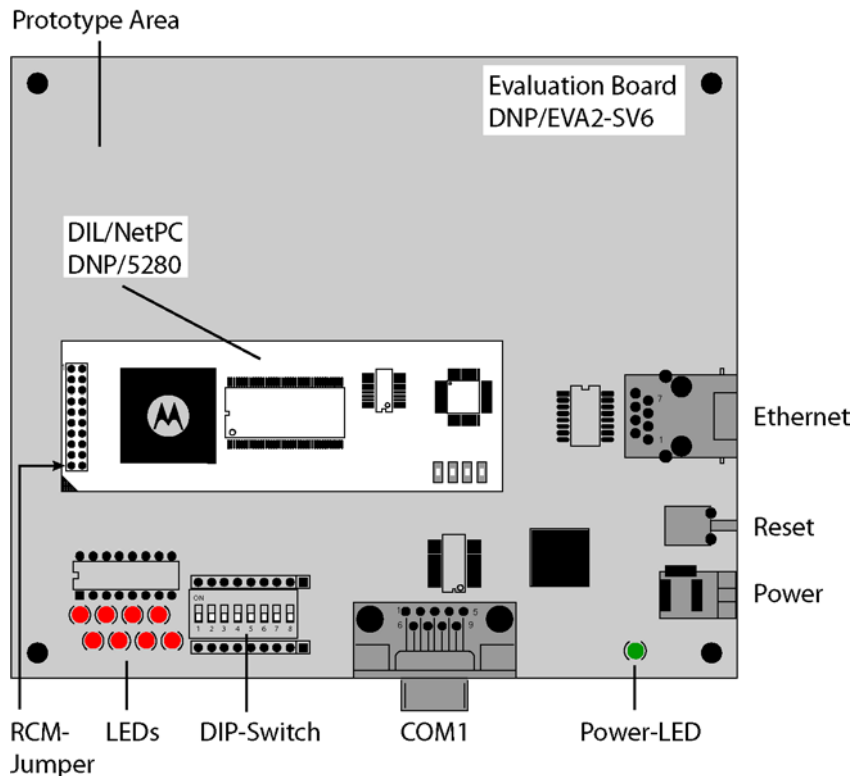


Figure 3-1: Main components of the Evaluation Board DNP/EVA2-SV6

The Evaluation Board offers a single 64-pin DIL socket (DIL = Dual-In-Line). This socket picks up your DNP/5280 and builds the interface to the individual parts on the Evaluation Board.

3.1 Power Connector

The Power connector onto the Evaluation Board has to be connected with the power supply, which is added to your Starter Kit. Alternatively you are able to use a similar power supply that provides +5V DC $\pm 10\%$ and approx. 1500 mA current.

3.2 Power LED

The Evaluation Board DNP/EVA2-SV6 is equipped with a single green LED. This LED will light up when the board is provided with the necessary operating voltage.

3.3 Output LEDs

The Evaluation Board provides eight red LEDs for testing purposes. These LEDs are the first little application for the PIO-Ports. The LEDs will flicker or light up to indicate traffic on the output ports PA0–PA7.

3.4 DIP Switches

The Evaluation Board has a set of eight DIP-switches. The DIP-switches give you the possibility to put 8-bit binary numbers to the input ports PB0–PB7. The DIP-switches are the second little application for the PIO ports.

Switch open = Signal Vin Low (GND)
Switch closed = Signal Vin High (Vcc)

3.5 Reset Button

Next to the Power connector you find the Reset button. Press it down if the system hangs or you need to restart it. Pressing the Reset button will only restart the DNP/5280. To reset any connected devices please turn off the complete power from the system.

3.6 Prototype Area

The Prototype Area offers space to develop your own applications and circuits on the Evaluation Board.

3.7 RCM Jumper

Note: The default setting of the RCM-jumper is not set. Only if the RCM-jumper is set you will be able to boot μ CLinux on the DNP/5280.

The **Remote Console Mode (RCM)** realizes some basic operating modes such as a boot loader or a ROM-Monitor Program. The default firmware of the DNP/5280 starts a ROM-Monitor (Motorola-dBUG) when the RCM-jumper is set. The DNP/5280 boots with μ CLinux when the RCM-jumper is not set.

Use this jumper (Pins 19 and 20 of the BDM-Interface) to activate RCM on the DNP/5280. To activate RCM place a jumper cap on both pins of the RCM-jumper, so that it is short. If you remove the jumper cap, or place the jumper cap on just one pin, the jumper is not set and you are not able to use RCM.

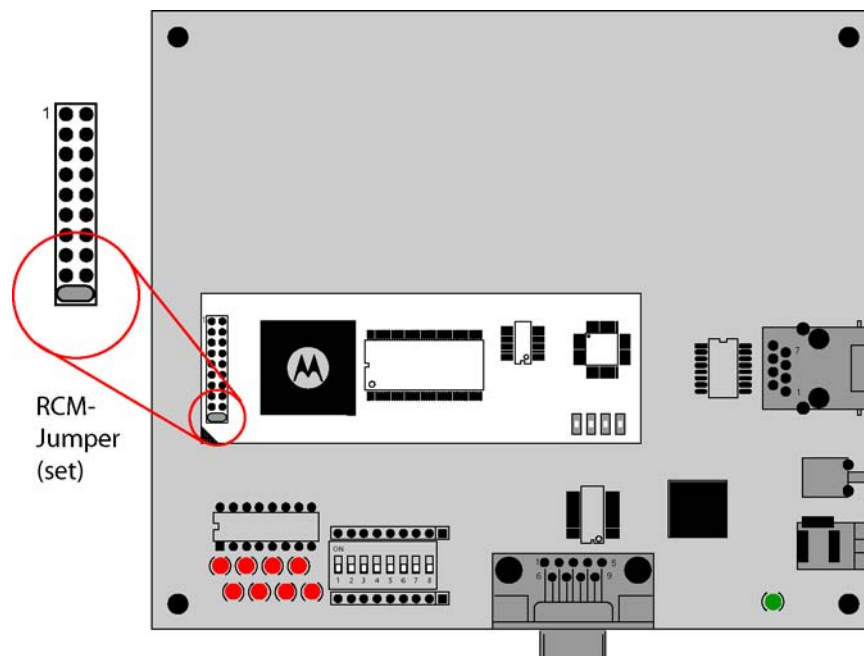


Figure 3-2: Position of the RCM-Jumper on the DNP/5280

3.8 10/100Mbps Ethernet Interface

The DNP/5280 is using a Realtek RTL8201BL PHY 10/100Mbps chip that allows Ethernet connectivity with a speed up to 100Mbps. The RJ45 Ethernet interface on the Evaluation Board is just a simple connection over a transformer to the DIL interface pins, which are connected to the LAN controller onto the DNP/5280.

Four miniature LEDs are placed on the DNP/5280 for a visual check of the LAN activity.

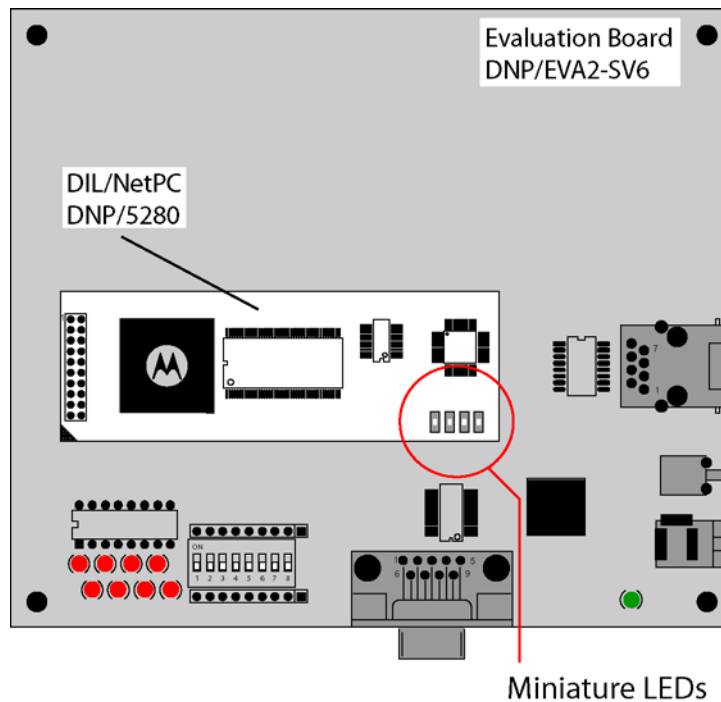


Figure 3-3: Position of the Miniature LEDs on the DNP/5280

3.9 Serial Interface COM1

For an easy connection between the Starter Kit and your development system you can use the serial interface COM1. The COM1 interface is realized as a RS232 standard compliant Sub-D port with 9 pins. The exact layout of the COM1 interface is shown in Appendix 2 - A2.1 COM1 Connector.

4 Connections

For a quick and easy start with the DNP/SK13 Starter Kit there are several connections necessary. The following chapter describes, how and between which components these connections have to be made.

4.1 Mounting the DNP/5280

To mount the DNP/5280 on the Evaluation Board DNP/EVA2-SV6 identify the pin 1 corner on the socket and the pin 1 corner on the DNP/5280. On the DNP/5280 a white sign marks the pin 1 corner. Matching the pin 1 corners, drop the DNP/5280 down into the socket. There is only a little bit force required and the DNP/5280 should seat easily into the socket. This locks the DNP/5280 in place.

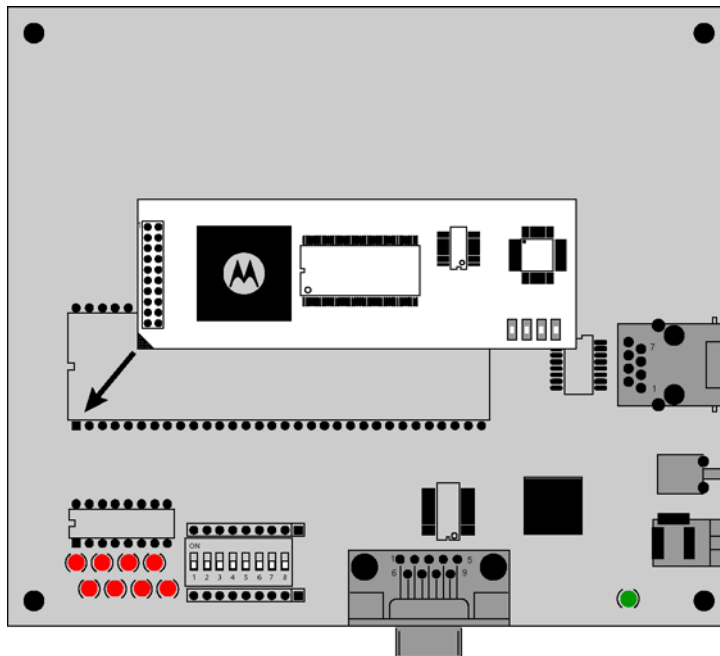


Figure 4-1: Position of the DNP/5280 on the Evaluation Board

4.2 Cable Connections

Before you can use your DIL/NetPC Starter Kit you need a further Desktop- or Notebook-PC, which acts as development system. This development system should run under MS-Windows or Linux in an ideal manner.

Between the development system and the Starter Kit are two connections required. At first the RS232 Serial Link and at second the Ethernet Link.

The PC will act as development system and as RCM (Remote Console Mode) for the DNP/5280 on the Evaluation Board.

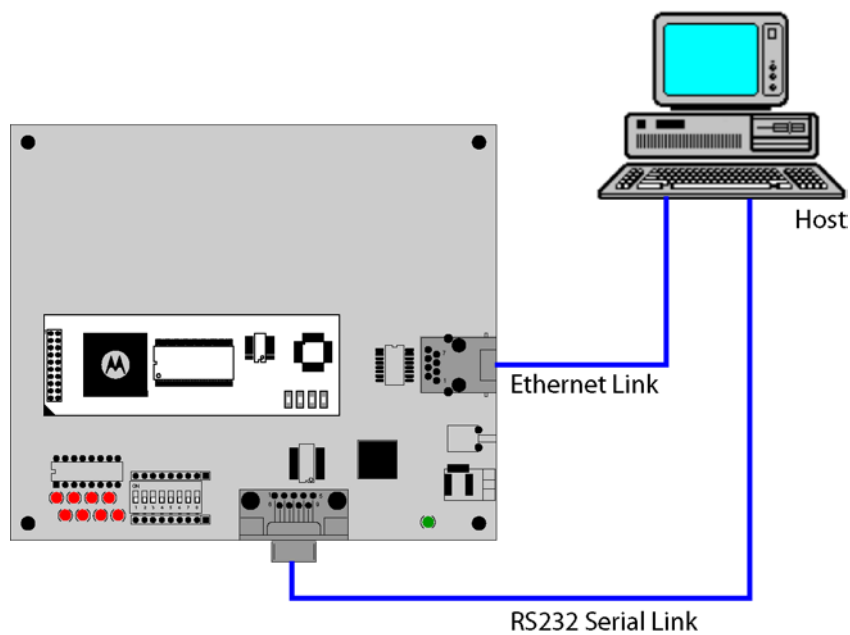


Figure 4-2: Overview about the required cable connections

4.3 Serial Link

For the Serial Link, you need a Null-Modem cable. This cable comes along with your Starter Kit. Please connect the Evaluation Board with the COM1 port of your development system by using this cable.

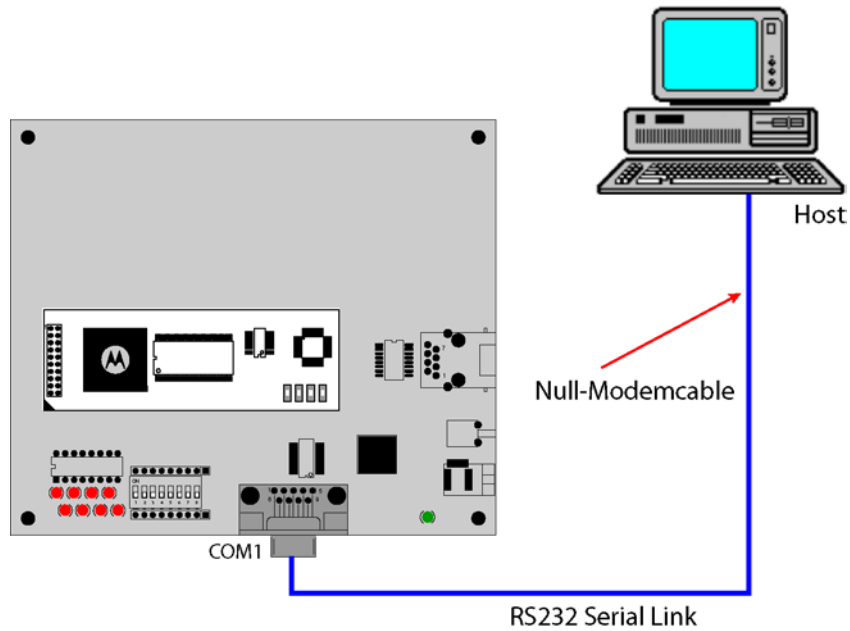


Figure 4-3: Serial Link Connection

4.4 Ethernet Link

The Ethernet Link can be made on two ways. First, with a Crossover Cable and second, with two standard 10/100Base T patch cables and a hub or switch. In both cases an Ethernet-LAN interface for your development system is required. If you use a hub or switch please connect them between your development system and the DNP/5280 like shown in the figure below.

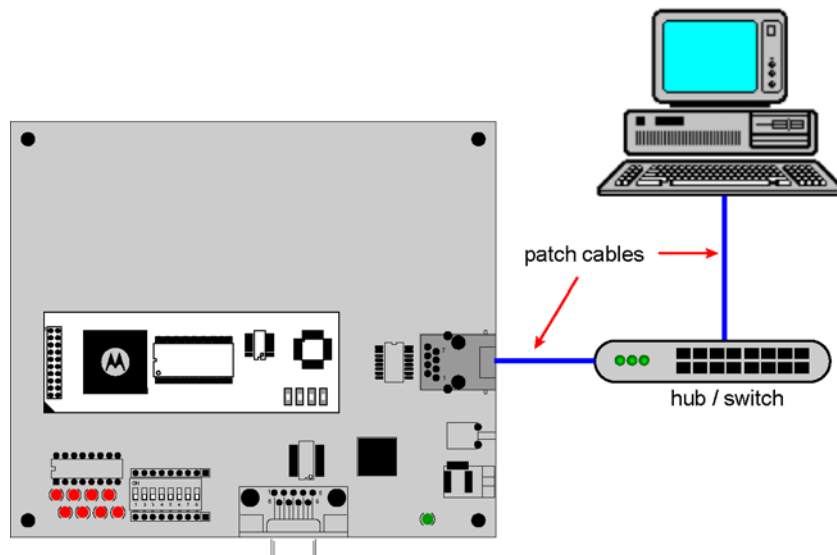


Figure 4-4: Ethernet Link Connection using a hub/switch

If you want to connect your development system directly to the DNP/5280, place a Crossover Cable between these two components like shown in the next figure.

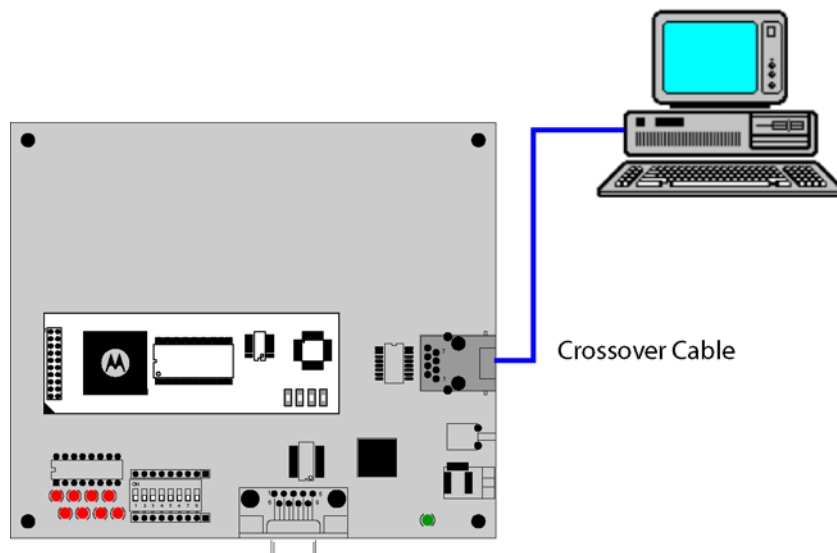


Figure 4-5: Ethernet Link Connection using a Crossover Cable

4.5 Power Supply

The DNP/5280 Starter Kit needs a supply voltage of 5V DC to work. In your Starter Kit package you will find a plug-in power supply unit to provide the system with the necessary power. After the connection of all cables the Starter Kit is ready to run.

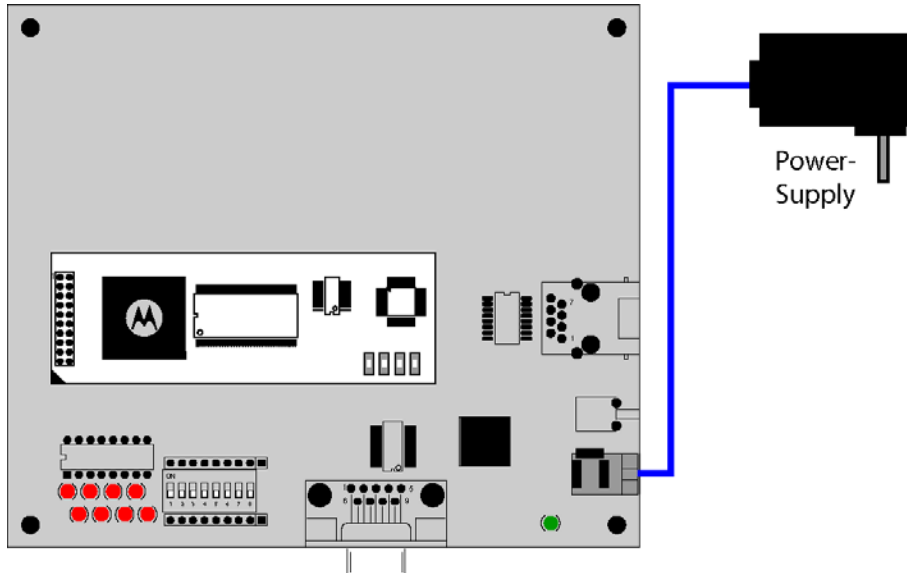


Figure 4-6: Power supply Connection

Caution:

Providing the Evaluation Board of the DNP/5280 with a voltage higher than the regular +5V DC $\pm 10\%$ could result in damaged board components!

5 First Steps

You can use the DNP/5280 Starter Kit from your development system. This development system may run under different operating systems. The first steps for getting started we describe exemplarily by the two most popular operating systems – MS-Windows and Linux.

5.1 Using a Windows–based development System

The following paragraphs will help you to use the DNP/5280 with a development system running under MS-Windows. For these steps some programs are necessary, which normally come along with every MS-Windows installation (e.g. **HyperTerminal**). Please make sure that these programs are present on your development system. If these programs are not installed at your development system – you have to install these programs manually from your MS-Windows installation CD-ROM.

5.1.1 Setup the Serial Link

Before you provide the Evaluation Board with power for the first time, please run a terminal program that offers communication capabilities on your development system – e.g. Windows HyperTerminal. In the following you will see the necessary settings for HyperTerminal under Windows. Select the "direct link cable connection via COM1" interface (or any other appropriate COM-port) in the dialog box and choose "OK".



Figure 5-1: Interface dialog box

Now you can change some configuration parameters – such as the maximum baud rate – on a further dialog box. Select the value "115 200" in the "Bits per Second" field and close the dialog box by clicking the "OK" button, as shown in the next figure.

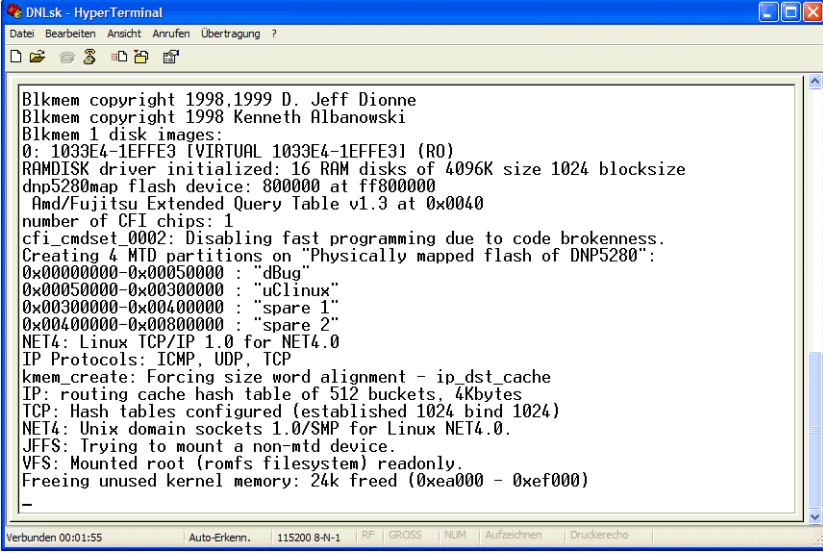


Figure 5-2: Communication parameter settings

All these settings can also be used for other terminal programs. The following parameters are important to use:

- Connection Speed 115.200 bps (Bits per Second)
- 8 Data bits
- No Parity bit
- 1 Stop bit
- No Protocol (Xon/Xoff, RTS/CTS or similar).

Now turn on the power for the Evaluation Board and you will see all steps of the DNP/5280 boot process in the terminal program window at your PC. If you do not see the following boot process, please assure that the RCM-jumper on the DNP/5280 is not set (please see chapter 3.7 for detailed information).



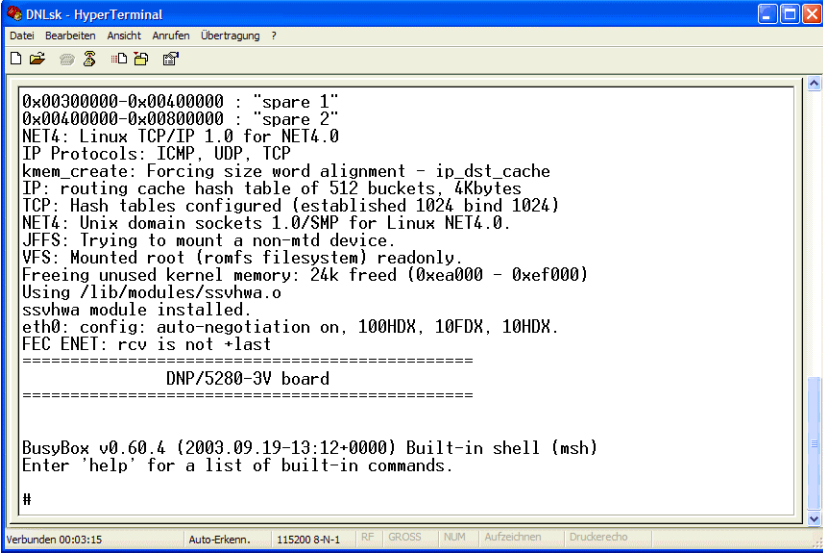
```

Blkmem copyright 1998,1999 D. Jeff Dionne
Blkmem copyright 1998 Kenneth Albanowski
Blkmem 1 disk images:
0: 1033E4-1EFFE3 [VIRTUAL 1033E4-1EFFE3] (R0)
RAMDISK driver initialized: 16 RAM disks of 4096K size 1024 blocksize
dnp5280map flash device: 800000 at ff800000
Amd/Fujitsu Extended Query Table v1.3 at 0x0040
number of CFI chips: 1
cfi_cmdset_0002: Disabling fast programming due to code brokenness.
Creating 4 MTD partitions on "Physically mapped flash of DNP5280":
0x00000000-0x00050000 : "dBug"
0x00050000-0x00300000 : "uCLinux"
0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)
-

```

Figure 5-3: Linux boot process

After the self test sequence is done the Linux boot process will be initialized. When finished, you will see the following screen with a Linux prompt which is waiting for a user input.



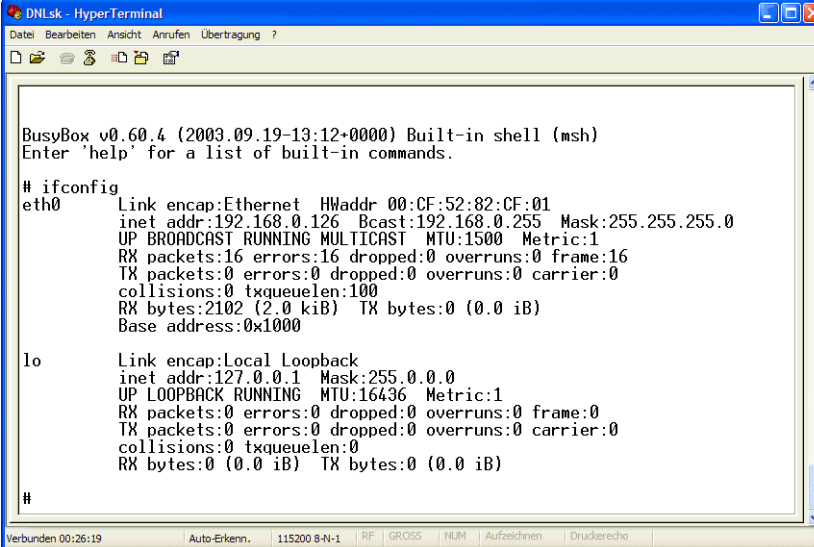
```

0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)
Using /lib/modules/ssvhw.a
ssvhw module installed.
eth0: config: auto-negotiation on, 100HDX, 10FDX, 10HDX.
FEC ENET: rcv is not +last
=====
DNP/5280-3V board
=====
BusyBox v0.60.4 (2003.09.19-13:12+0000) Built-in shell (msh)
Enter 'help' for a list of built-in commands.
#

```

Figure 5-4: Linux command prompt

Now please enter *ifconfig* to see the network interface addresses of the DNP/5280.



```

DNLsk - HyperTerminal
Datei Bearbeiten Ansicht Anrufen Übertragung ?
BusyBox v0.60.4 (2003.09.19-13:12:0000) Built-in shell (msh)
Enter 'help' for a list of built-in commands.
# ifconfig
eth0 Link encap:Ethernet HWaddr 00:CF:52:82:CF:01
      inet addr:192.168.0.126 Bcast:192.168.0.255 Mask:255.255.255.0
      UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
      RX packets:16 errors:16 dropped:0 overruns:0 frame:16
      TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
      collisions:0 txqueuelen:100
      RX bytes:2102 (2.0 kiB) TX bytes:0 (0.0 iB)
      Base address:0x1000

lo Link encap:Local Loopback
     inet addr:127.0.0.1 Mask:255.0.0.0
     UP LOOPBACK RUNNING MTU:16436 Metric:1
     RX packets:0 errors:0 dropped:0 overruns:0 frame:0
     TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
     collisions:0 txqueuelen:0
     RX bytes:0 (0.0 iB) TX bytes:0 (0.0 iB)

#
  
```

Figure 5-5: DNP/5280 network interface addresses

Note: For a first test of the Ethernet connection between the development system and the DNP/5280 you have to change the assigned IP-address of your development system to 192.168.0.254.

To change the IP-address under MS-Windows just click "Start → Settings → Control Panel → Network → TCP/IP" and enter the new IP-address. Please make sure, that you do not use another IP-address – this will lead to different network problems.

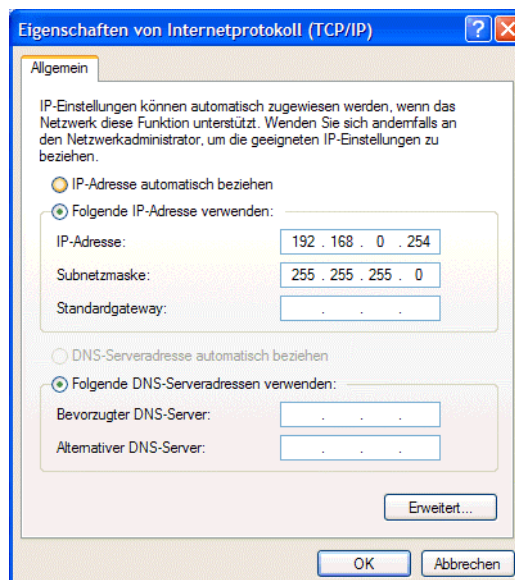
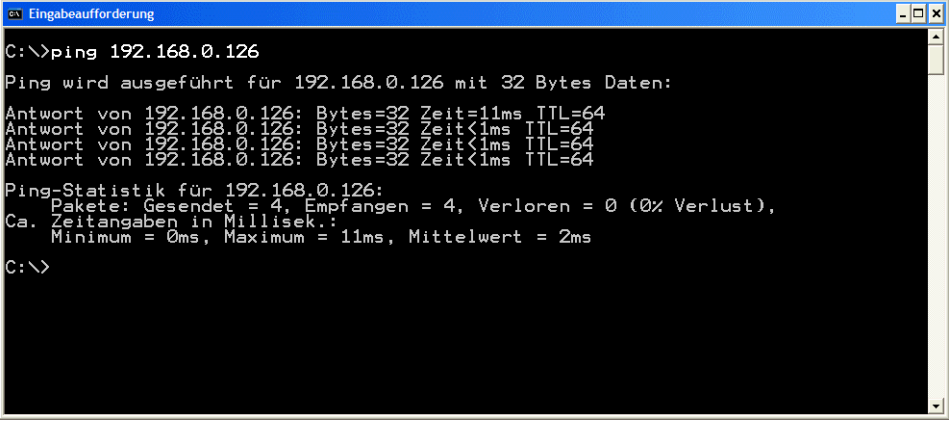


Figure 5-6: Windows IP address settings

5.1.2 Checking the Ethernet Link

To test the TCP/IP-communication we use PING a very popular TCP/IP-utility program. Please open a DOS window (you can find it in the Windows Start menu) and enter:

```
ping 192.168.0.126
```

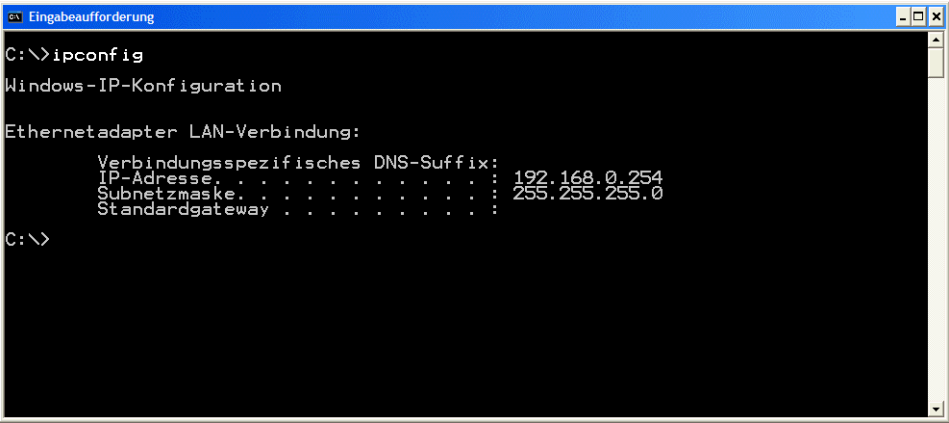


```
Eingabeaufforderung
C:\>ping 192.168.0.126
Ping wird ausgeführt für 192.168.0.126 mit 32 Bytes Daten:
Antwort von 192.168.0.126: Bytes=32 Zeit=11ms TTL=64
Antwort von 192.168.0.126: Bytes=32 Zeit<1ms TTL=64
Antwort von 192.168.0.126: Bytes=32 Zeit<1ms TTL=64
Antwort von 192.168.0.126: Bytes=32 Zeit<1ms TTL=64
Ping-Statistik für 192.168.0.126:
    Pakete: Gesendet = 4, Empfangen = 4, Verloren = 0 (0% Verlust),
    Ca. Zeitangaben in Millisek.:
        Minimum = 0ms, Maximum = 11ms, Mittelwert = 2ms
C:\>
```

Figure 5-7: Communication check via PING

The Starter Kit must answer this ping. Otherwise an error will occur. In this case you have to check all parts of your LAN-connection, including the IP-address of the development system. The correct value of the IP-address is "192.168.0.254". For an easy check of the IP-address within the DOS window, you can use the following DOS-command:

```
ipconfig
```



```
Eingabeaufforderung
C:\>ipconfig
Windows-IP-Konfiguration

Ethernetadapter LAN-Verbindung:

    Verbindungsspezifisches DNS-Suffix:
    IP-Adresse. . . . . : 192.168.0.254
    Subnetzmaske. . . . . : 255.255.255.0
    Standardgateway . . . . . :

C:\>
```

Figure 5-8: Communication check via ipconfig command

Once the ping was successful, you are ready to start a Web browser on your development PC. This browser may be the Microsoft Internet Explorer or a different suitable Web browser like the Netscape Communicator or Opera or similar.

5.1.3 Web Server Access

Start a Web browser like the Microsoft Internet Explorer or similar and open the URL ***http://192.168.0.126***. The Embedded Web Server will deliver you a small de-scription about the DNP/5280. That's it. Now you are online with the Starter Kit and your Web browser is connected to the Embedded Web Server of the DNP/5280. It shows you a static web page with some pictures.

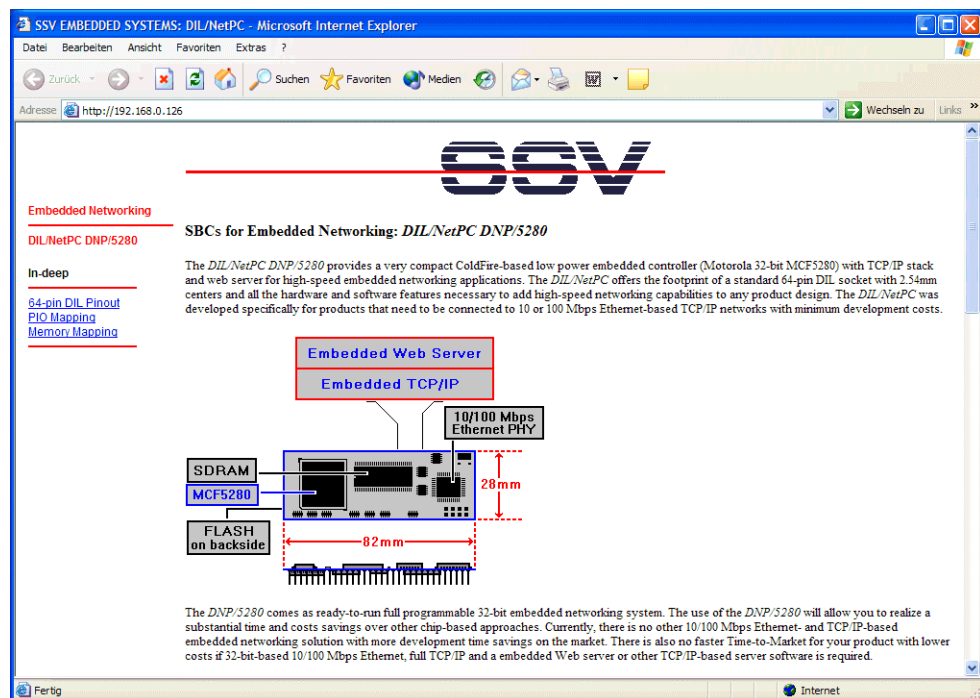


Figure 5-9: Web page shown by the MS-Internet Explorer

If your Web browser can't establish a connection to the Web Server – but the Ping was successful – you should check your browser settings. Please ensure that your browser is joined with TCP/IP by using the Ethernet card in your development system. Alternatively you have to install a suitable Web browser.

Please make sure that your Web browser does not use an Internet Proxy Server for http-requests. See the Web browser connection settings for further details.

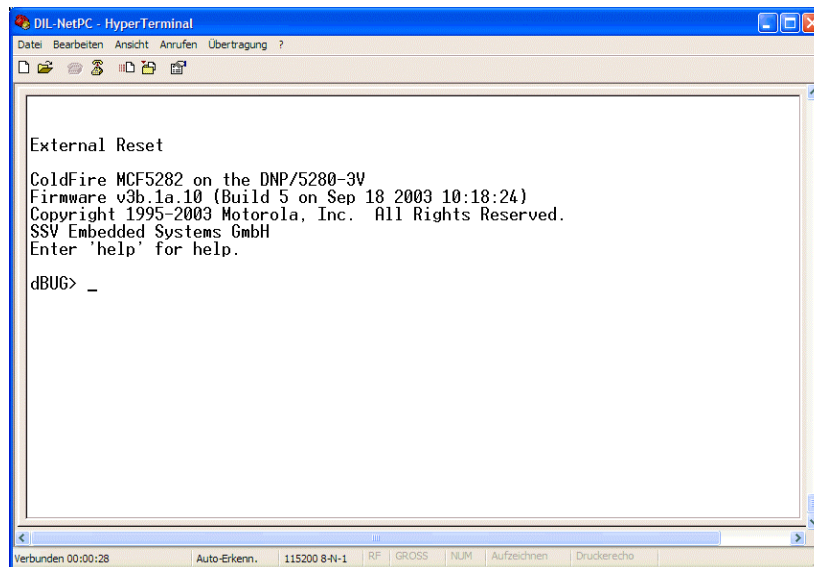
In some cases the Web browser is only configured for modem based Internet access. In this case, please install a second Web browser from your original operating system CD-ROM.

5.1.4 Assigning a new IP-Address to the DNP/5280

The following steps describe how to change the IP-address of the DNP/5280 with a terminal program like the HyperTerminal-program in MS-Windows.

Note: Please assure that the RCM-jumper on the DNP/5280 is set for further operation. Please see chapter 3.7 how to set the RCM-jumper correctly.

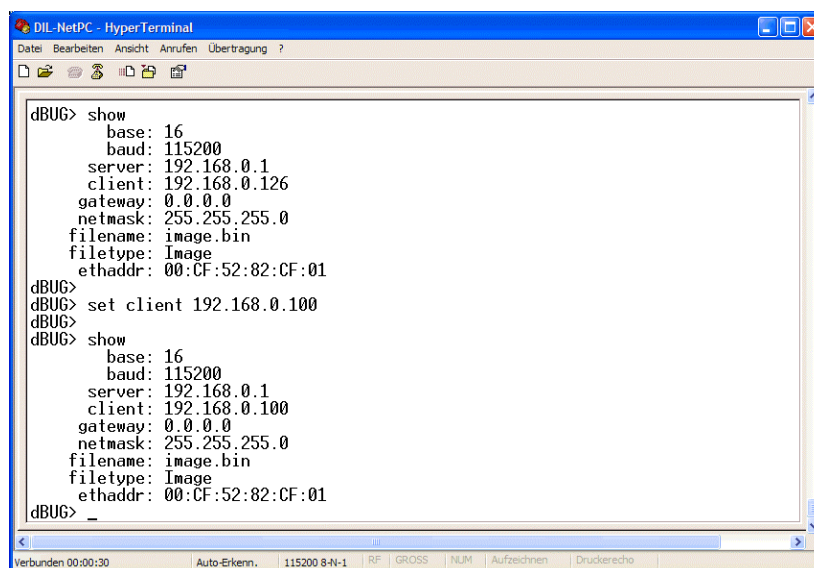
When the DNP/5280 has booted with the RCM-jumper set you should see the following screen on your terminal program.



```
DIL-NetPC - HyperTerminal
Datei Bearbeiten Ansicht Anrufen Übertragung ?
External Reset
ColdFire MCF5282 on the DNP/5280-3V
Firmware v3b_1a_10 (Build 5 on Sep 18 2003 10:18:24)
Copyright 1995-2003 Motorola, Inc. All Rights Reserved.
SSV Embedded Systems GmbH
Enter 'help' for help.
dBUG> _
Verbunden 00:00:28 Auto-Erkenn. 115200 8-N-1 RF | GROSS NUM Aufzeichnen Druckerecho
```

Figure 5-10: Boot process with RCM-jumper set

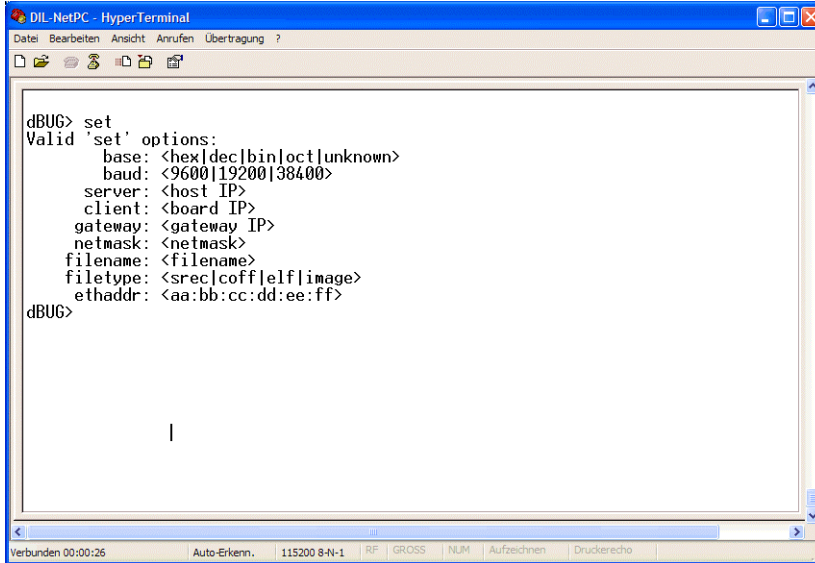
Now enter the command *show* to see the current parameters of the DNP/5280. To assign a different IP-address (e.g. the IP-address 192.168.0.100) use the Linux command *set client 192.168.0.100*.



```
DIL-NetPC - HyperTerminal
Datei Bearbeiten Ansicht Anrufen Übertragung ?
dBUG> show
base: 16
baud: 115200
server: 192.168.0.1
client: 192.168.0.126
gateway: 0.0.0.0
netmask: 255.255.255.0
filename: image.bin
filetype: Image
ethaddr: 00:CF:52:82:CF:01
dBUG>
dBUG> set client 192.168.0.100
dBUG>
dBUG> show
base: 16
baud: 115200
server: 192.168.0.1
client: 192.168.0.100
gateway: 0.0.0.0
netmask: 255.255.255.0
filename: image.bin
filetype: Image
ethaddr: 00:CF:52:82:CF:01
dBUG> _
Verbunden 00:00:30 Auto-Erkenn. 115200 8-N-1 RF | GROSS NUM Aufzeichnen Druckerecho
```

Figure 5-11: Assigning a new IP-address to the DNP/5280

Probably you have to change other parameters as well. The next figure shows you how to use the command set with different parameters.



```
dBUG> set
Valid 'set' options:
    base: <hex|dec|bin|oct|unknown>
    baud: <9600|19200|38400>
    server: <host IP>
    client: <board IP>
    gateway: <gateway IP>
    netmask: <netmask>
    filename: <filename>
    filetype: <srec|coff|elf|image>
    ethaddr: <aa:bb:cc:dd:ee:ff>
dBUG>
```

Figure 5-12: Command set with parameters

5.1.5 Running Linux

The DNP/5280 is delivered with a pre-installed Linux. When booting make sure the RCM-jumper of the DNP/5280 is not set. When the Linux boot process is done the system will stop with the login prompt shown in figure 5 13.

The DNP/5280 Linux does not need a user login with user name and password. Just enter your Linux commands directly after the boot process.

Note: On every boot process without the RCM-jumper set (please see chapter 3.7) there is a serial console available with following parameters: 115 200 bps, No Parity, 8 Data Bits, 1 Stop Bit, No Handshake.

```

DNLsk - HyperTerminal
Datei Bearbeiten Ansicht Anrufen Übertragung ?
0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)
Using /lib/modules/ssvhw.o
ssvhw module installed.
eth0: config: auto-negotiation on, 100HDX, 10FDX, 10HDX.
FEC ENET: rcv is not +last

=====
DNP/5280-3V board
=====

BusyBox v0.60.4 (2003.09.19-13:12+0000) Built-in shell (msh)
Enter 'help' for a list of built-in commands.

#

```

Figure 5-13: DNP/5280 Linux boot process

Alternatively you can use a **Command Line Interface (CLI)** like a Telnet client to communicate with the DNP/5280. Open for example a DOS window in MS-Windows and type in the command **telnet 192.168.0.126**.

If you have already assigned a different IP-address to the DNP/5280 you need to enter this new IP-address in the command line.

```

Eingabeaufforderung
C:\>telnet 192.168.0.126_

```

Figure 5-14: Running the MS-Windows Telnet client

Within the Telnet client you can enter Linux commands that will be executed by the DNP/5280. The standard output will be shown in your Telnet client window as illustrated in the next figure.

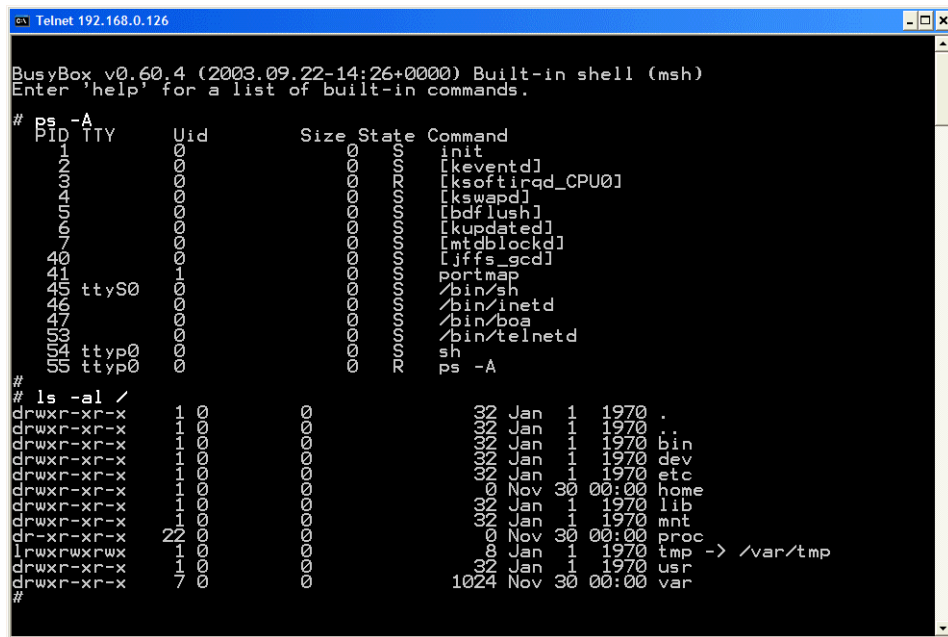


Figure 5-15: Enter Linux commands via Telnet

Note: You can enter Linux commands in different Command Line Interfaces (CLI) like a serial console (e.g. HyperTerminal, Minicom) or a Telnet client.

5.1.6 File Transfer via TFTP

The DIL/NetPC DNP/5280 offers a very simple way for Ethernet-based file transfers between your PC system and the DNP/5280 RAM disk drives or JFFS-based flash disk drives. This file transfer is using the TCP/IP service **TFTP (Trivial File Transfer Protocol)**.

TFTP is server/client-based. The DIL/NetPC DNP/5280 Linux configuration offers a TFTP client program. Your PC needs a TFTP server program.

Note: Windows-based PCs do not offer TFTP server programs. Only some special server versions of MS Windows come with a TFTP server program. For all other Windows-based PCs you find a simple TFTP server program – TFTP32 – within the directory `\TFTP-Server-Win32` of your DNP/5280 Starter Kit CD-ROM. Copy all files from `\TFTP-Server-Win32` to a new subdirectory on your Windows-based PC hard disk drive. TFTP32 is a free, non-commercial product. Please watch the license.

First you have to set-up an Ethernet link between the DNP/5280 10/100 Mbps Ethernet interface and the Ethernet interface of your PC system. Check the IP address of your Windows PC system with the *ipconfig* command. The default IP address (factory setup) of the DNP/5280 is 192.168.0.126.

Now run the TFTP server program on your PC system.

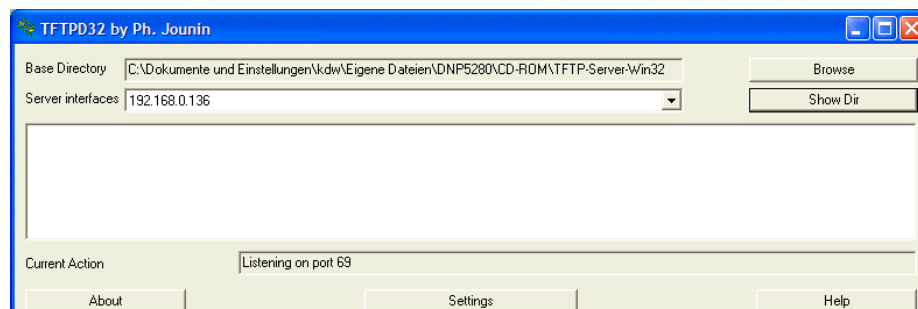


Figure 5 16: Running TFTP32

Check the TFTP connection between the DIL/NetPC DNP/5280 and your PC system. Open a Telnet session and use the following commands for downloading and uploading files:

```
tftp -g -l file.name ip-addr
tftp -p -l file.name ip-addr
```

The command *tftp* is the name of the DNP/5280 TFTP client program.

The parameter *-g* stands for get (get a file from the PC system to the DNP/5280).

The parameter *-p* stands for put (put a file from the DNP/5280 to the PC system).

The parameter *-l file.name* specifies the file for put or get.

The parameter *ip-addr* stands for the IP address of your PC system (i.e. 192.168.0.1).

Most TFTP server programs work with a default directory for put and get commands. Each TFTP put command writes a file to this directory. Each TFTP get command reads the file from this directory on your PC system. For TFTP32 you can change this directory with the browse button.

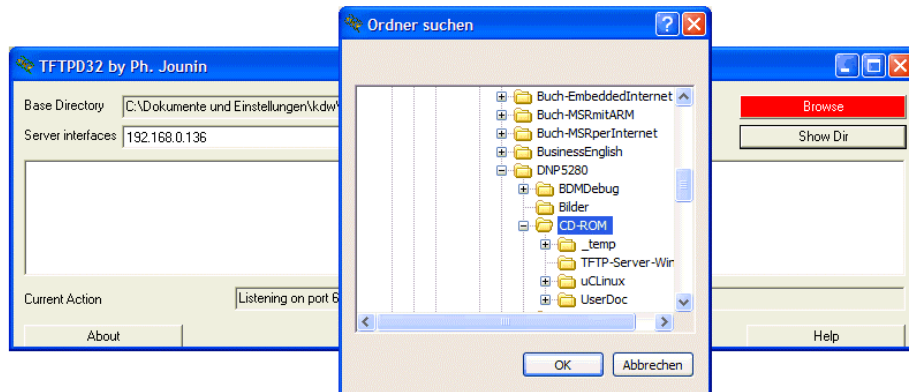


Figure 5 17: Changing the default directory for TFTP32

Example:

The following picture shows the use of the DNP/5280 TFTP client within a Telnet session.

```

Telnet 192.168.0.126
# pwd
/home/httpd
# ls -al
drwxr-xr-x  1 0 0 0 Nov 30 00:03 .
drwxr-xr-x  1 0 0 0 Nov 30 00:00 ..
-rw-r--r--  497 Nov 30 00:07 boa.conf
-rw-r--r--  4850 Nov 30 00:10 dnp5280-1.gif
-rw-r--r--  7904 Nov 30 00:10 index.html
-rw-r--r--  4091 Nov 30 00:11 memmap.html
-rw-r--r--  11235 Nov 30 00:11 pinout.html
-rw-r--r--  4766 Nov 30 00:11 pio.html
-rw-r--r--  1771 Nov 30 00:10 spacer2.gif
-rw-r--r--  769 Nov 30 00:07 ssvlogo.gif
# tftp -p -l ssvlogo.gif 192.168.0.1
# tftp -p -l spacer2.gif 192.168.0.1
#
  
```

Figure 5 18: Using the DNP/5280 TFTP client within a Telnet session

Note: A file transfer to the DNP/5280 must be started with a Telnet session from RAM disk or JFFS-based flash disk directories. You need R/W access for the TFTP get command.

5.2 Using a Linux-based development System

The following paragraphs will help you to use the DNP/5280 with a development system running under Linux. For these steps you will need some programs, which normally come along with the Linux installation (i.e. **Minicom**). Please make sure that these programs are present on your development system.

If necessary you have to install these programs from your Linux installation CD-ROM.

5.2.1 Setup the Serial Link

Before you provide the Evaluation Board with power for the first time, please run a terminal program like Minicom. Minicom is a simple serial communication program originally written by Miquel van Smoorenburg. It offers basic communication capabilities and integrates well with the Linux user interface. Minicom is a lot like the old MS-DOS program PROCOMM. This program can be used to connect a Linux-based PC to embedded devices such as the DNP/5280 for initial configurations. In the following we will show you how to use Minicom and what you have to do to adjust the necessary settings.

Open a terminal window and type in the command **minicom -s** to get access to the serial port settings. Now you can change some configuration parameters – such as the maximum baud rate. Set the serial port parameters for the maximum baud rate on "115.200 bps".

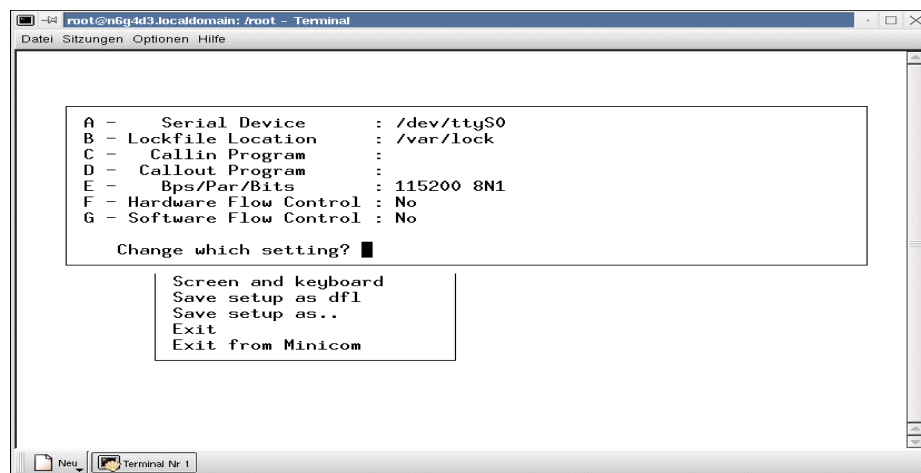
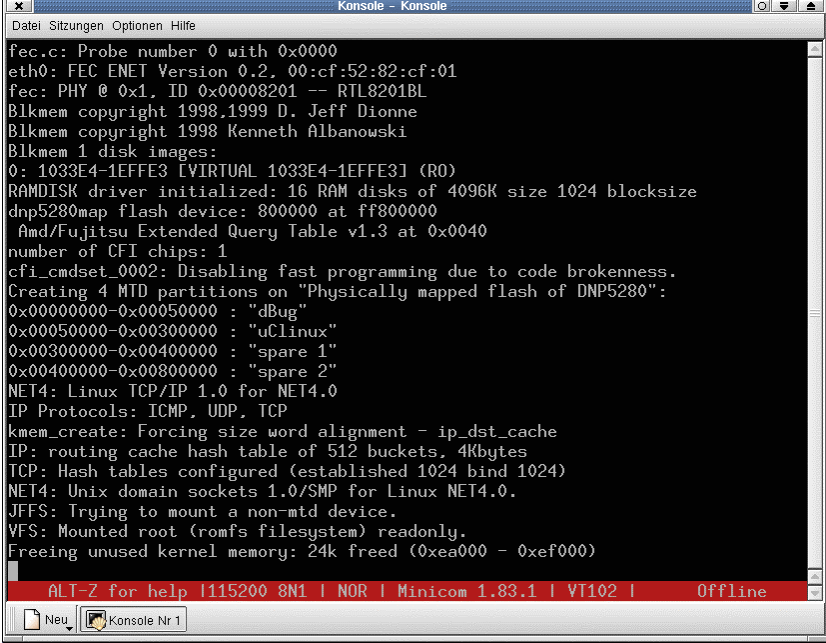


Figure 5-19: Serial Port Settings under Minicom

Now turn on the power for the Evaluation Board and you will see all steps of the DNP/5280 boot process in the terminal program window at your PC. If you do not see the following boot process, please assure that the RCM-jumper on the DNP/5280 is not set.



```

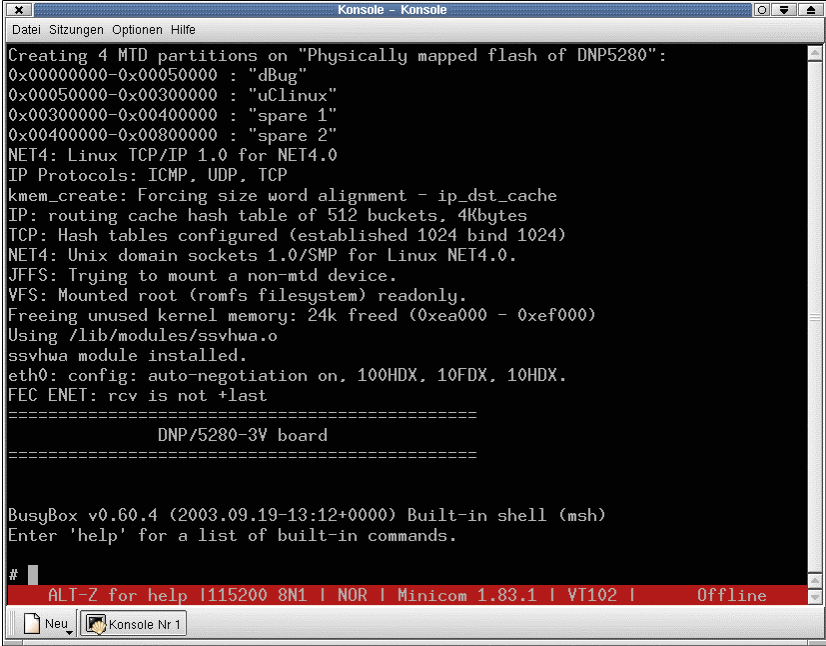
Datei Sitzungen Optionen Hilfe
fec.c: Probe number 0 with 0x0000
eth0: FEC ENET Version 0.2, 00:cf:52:82:cf:01
fec: PHY @ 0x1, ID 0x00008201 -- RTL8201BL
Blkmem copyright 1998,1999 D. Jeff Dionne
Blkmem copyright 1998 Kenneth Albanowski
Blkmem 1 disk images:
0: 1033E4-1EFFE3 [VIRTUAL 1033E4-1EFFE3] (R0)
RAMDISK driver initialized: 16 RAM disks of 4096K size 1024 blocksize
dnp5280map flash device: 800000 at ff800000
Amd/Fujitsu Extended Query Table v1.3 at 0x0040
number of CFI chips: 1
cfi_cmdset_0002: Disabling fast programming due to code brokenness.
Creating 4 MTD partitions on "Physically mapped flash of DNP5280":
0x00000000-0x00050000 : "dBug"
0x00050000-0x00300000 : "uClinux"
0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)

ALT-Z for help |115200 8N1 | NOR | Minicom 1.83.1 | VT102 | Offline

```

Figure 5-20: Linux boot process

After the self test sequence is done the Linux boot process will be initialized. When finished, you will see the following screen with a Linux prompt waiting for a user input.



```

Datei Sitzungen Optionen Hilfe
Creating 4 MTD partitions on "Physically mapped flash of DNP5280":
0x00000000-0x00050000 : "dBug"
0x00050000-0x00300000 : "uClinux"
0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)
Using /lib/modules/ssvhwa.o
ssvhwa module installed.
eth0: config: auto-negotiation on, 100HDX, 10FDX, 10HDX.
FEC ENET: rcv is not +last

=====
DNP/5280-3V board
=====

BusyBox v0.60.4 (2003.09.19-13:12+0000) Built-in shell (msh)
Enter 'help' for a list of built-in commands.

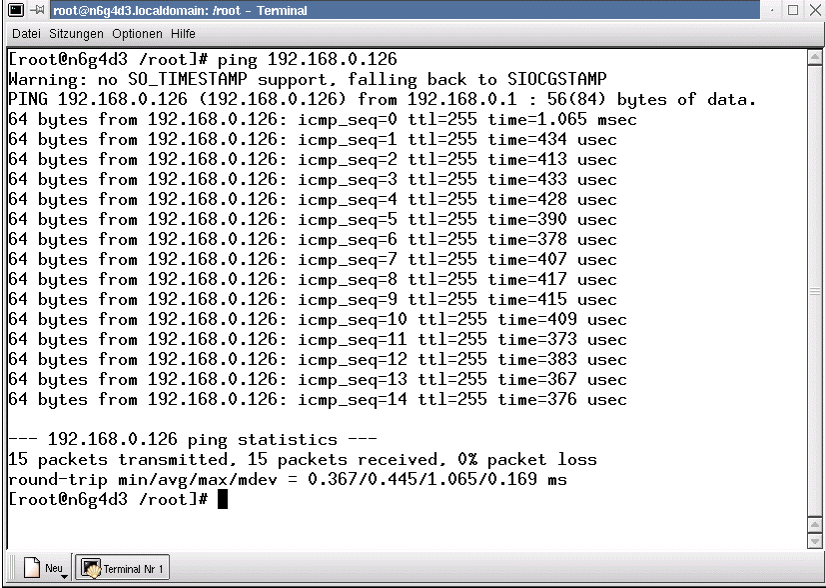
#
ALT-Z for help |115200 8N1 | NOR | Minicom 1.83.1 | VT102 | Offline

```

Figure 5-21: Linux command prompt

5.2.2 Checking the Ethernet Link

Please open a shell window and type in ping 192.168.0.126. Every ping request has to be answered by your DNP/5280 similar as shown below.



```

root@n6g4d3.localdomain: /root - Terminal
Datei Sitzungen Optionen Hilfe

[root@n6g4d3 /root]# ping 192.168.0.126
Warning: no SO_TIMESTAMP support, falling back to SIOCGSTAMP
PING 192.168.0.126 (192.168.0.126) from 192.168.0.1 : 56(84) bytes of data.
64 bytes from 192.168.0.126: icmp_seq=0 ttl=255 time=1.065 msec
64 bytes from 192.168.0.126: icmp_seq=1 ttl=255 time=434 usec
64 bytes from 192.168.0.126: icmp_seq=2 ttl=255 time=413 usec
64 bytes from 192.168.0.126: icmp_seq=3 ttl=255 time=433 usec
64 bytes from 192.168.0.126: icmp_seq=4 ttl=255 time=428 usec
64 bytes from 192.168.0.126: icmp_seq=5 ttl=255 time=390 usec
64 bytes from 192.168.0.126: icmp_seq=6 ttl=255 time=378 usec
64 bytes from 192.168.0.126: icmp_seq=7 ttl=255 time=407 usec
64 bytes from 192.168.0.126: icmp_seq=8 ttl=255 time=417 usec
64 bytes from 192.168.0.126: icmp_seq=9 ttl=255 time=415 usec
64 bytes from 192.168.0.126: icmp_seq=10 ttl=255 time=409 usec
64 bytes from 192.168.0.126: icmp_seq=11 ttl=255 time=373 usec
64 bytes from 192.168.0.126: icmp_seq=12 ttl=255 time=383 usec
64 bytes from 192.168.0.126: icmp_seq=13 ttl=255 time=367 usec
64 bytes from 192.168.0.126: icmp_seq=14 ttl=255 time=376 usec

--- 192.168.0.126 ping statistics ---
15 packets transmitted, 15 packets received, 0% packet loss
round-trip min/avg/max/mdev = 0.367/0.445/1.065/0.169 ms
[root@n6g4d3 /root]#

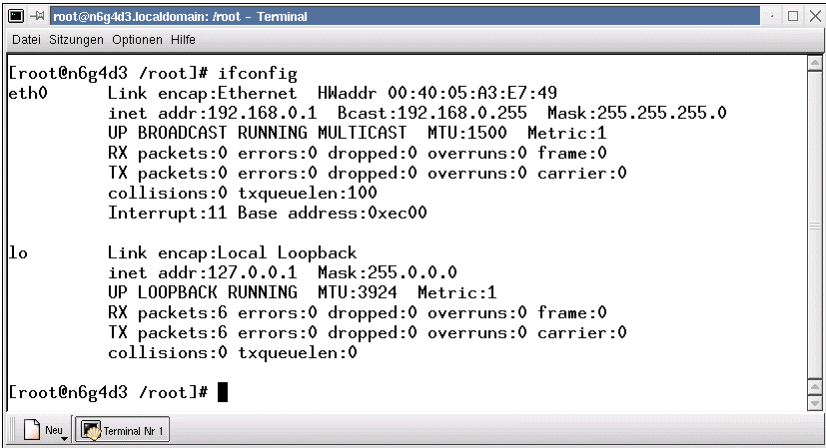
```

Figure 5-22: Ping Request

To cancel the ping request just press the keyboard shortcut C+c. If an error occurs (e.g. the DNP/5280 does not answer the ping of your development system) you have to check your cable connections at first.

Note: For a first test of the DNP/5280 you have to change the assigned IP-address of your development system to **192.168.0.1**. Please make sure, that you do not use another IP-address – this could lead to different network problems.

For an easy check if the IP-address is set correctly to "192.168.0.1", you can use the Linux-command *ifconfig*.



```

root@n6g4d3.localdomain: /root - Terminal
Datei Sitzungen Optionen Hilfe

[root@n6g4d3 /root]# ifconfig
eth0      Link encap:Ethernet  HWaddr 00:40:05:A3:E7:49
          inet addr:192.168.0.1  Bcast:192.168.0.255  Mask:255.255.255.0
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:100
          Interrupt:11 Base address:0xec00

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          UP LOOPBACK RUNNING  MTU:3924  Metric:1
          RX packets:6 errors:0 dropped:0 overruns:0 frame:0
          TX packets:6 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0

[root@n6g4d3 /root]#

```

Figure 5-23: IP-address check via ifconfig

5.2.3 Web Server Access

Once the ping was successful, you are ready to start a Web browser on your development system. This may be the Konqueror File Manager or the Netscape Communicator/Navigator. The Konqueror File Manager is normally part of the Linux installation and acts as File Manager as well as Web browser. Konqueror is able to detect automatically when an URL is entered and shows the content.

Just enter the URL ***http://192.168.0.126*** and press E. The Embedded Web Server will deliver you a small description about the DNP/5280.

That's it. You are now online with the Starter Kit. The Web browser of your development system is connected to the Embedded Web Server of the DNP/5280 and shows you a static web page with some pictures.

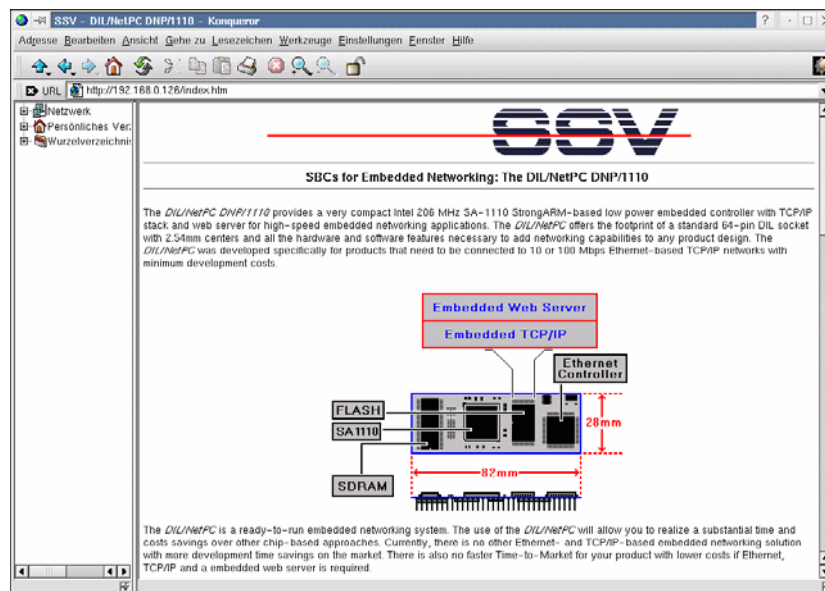


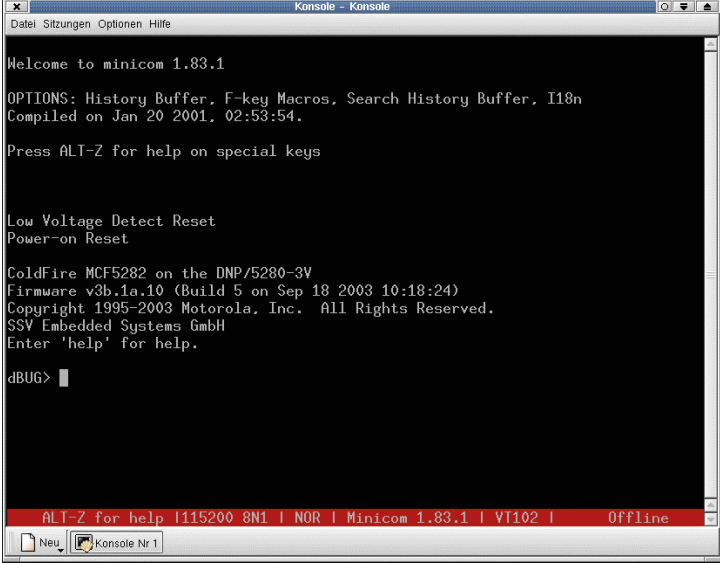
Figure 5-24: Web page shown by the Konqueror File Manager

5.2.4 Assigning a new IP-Address to the DNP/5280

The following steps describe how to change the IP-address of the DNP/5280 with a Command Line Interface like Minicom in Linux.

Note: Please assure that the RCM-jumper on the DNP/5280 is set for further operation. Please see chapter 3.7 how to set the RCM-jumper correctly.

When the DNP/5280 has booted with the RCM-jumper set you should see the following screen on your terminal program.



```

Welcome to minicom 1.83.1
OPTIONS: History Buffer, F-key Macros, Search History Buffer, I18n
Compiled on Jan 20 2001, 02:53:54.
Press ALT-Z for help on special keys

Low Voltage Detect Reset
Power-on Reset

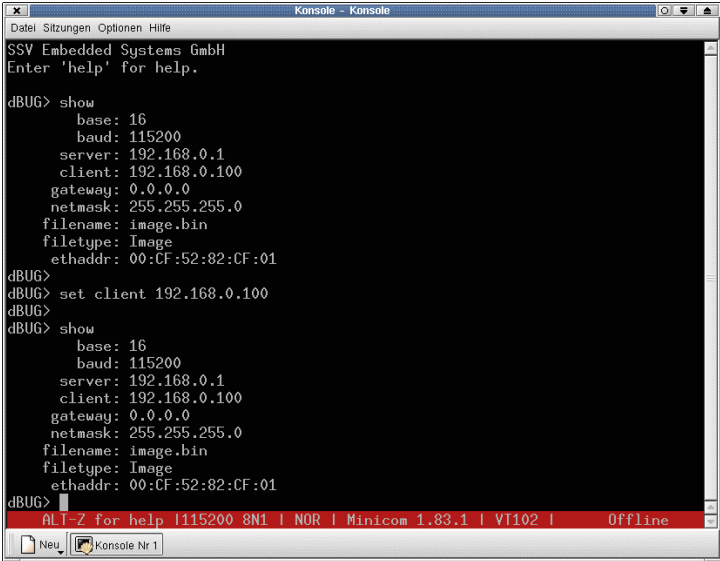
ColdFire MCF5282 on the DNP/5280-3V
Firmware v3b.1a.10 (Build 5 on Sep 18 2003 10:18:24)
Copyright 1995-2003 Motorola, Inc. All Rights Reserved.
SSV Embedded Systems GmbH
Enter 'help' for help.

dBUG>

```

Figure 5-25: Boot process with RCM-jumper set

Now enter the command *show* to see the current parameters of the DNP/5280. To assign a different IP-address (e.g. the IP-address 192.168.0.100) type in the command line *set client 192.168.0.100*.



```

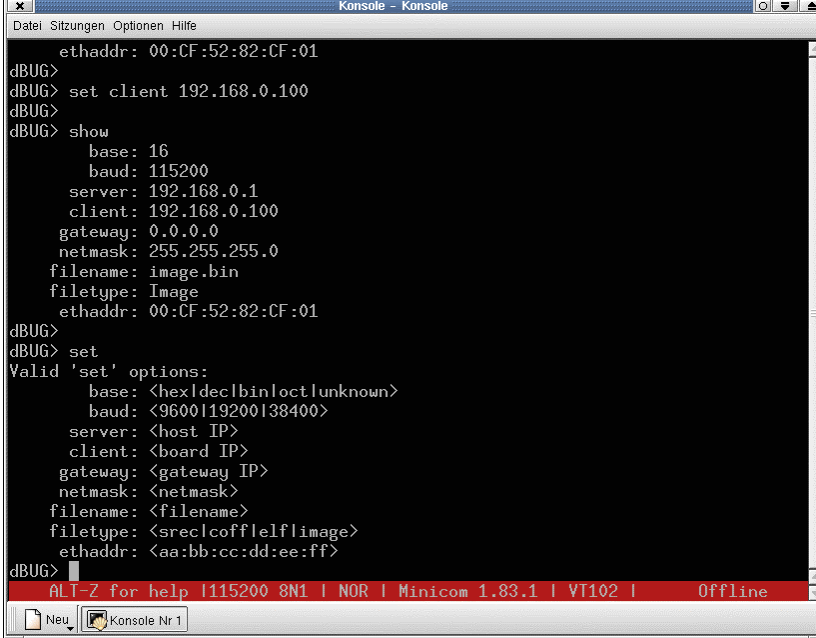
SSV Embedded Systems GmbH
Enter 'help' for help.

dBUG> show
  base: 16
  baud: 115200
  server: 192.168.0.1
  client: 192.168.0.100
  gateway: 0.0.0.0
  netmask: 255.255.255.0
  filename: image.bin
  filetype: Image
  ethaddr: 00:CF:52:82:CF:01
dBUG>
dBUG> set client 192.168.0.100
dBUG>
dBUG> show
  base: 16
  baud: 115200
  server: 192.168.0.1
  client: 192.168.0.100
  gateway: 0.0.0.0
  netmask: 255.255.255.0
  filename: image.bin
  filetype: Image
  ethaddr: 00:CF:52:82:CF:01
dBUG>

```

Figure 5-26: Assigning a new IP-address to the DNP/5280

Probably you have to change other parameters as well. The next figure shows you how to use the command set with different parameters.



```
Konsole - Konsole
Datei Sitzungen Optionen Hilfe
ethaddr: 00:CF:52:82:CF:01
dBUG>
dBUG> set client 192.168.0.100
dBUG>
dBUG> show
    base: 16
    baud: 115200
    server: 192.168.0.1
    client: 192.168.0.100
    gateway: 0.0.0.0
    netmask: 255.255.255.0
    filename: image.bin
    filetype: Image
    ethaddr: 00:CF:52:82:CF:01
dBUG>
dBUG> set
Valid 'set' options:
    base: <hex|dec|bin|oct|unknown>
    baud: <9600|19200|38400>
    server: <host IP>
    client: <board IP>
    gateway: <gateway IP>
    netmask: <netmask>
    filename: <filename>
    filetype: <src|coff|elf|image>
    ethaddr: <aa:bb:cc:dd:ee:ff>
dBUG>
```

ALT-Z for help | 115200 8N1 | NOR | Minicom 1.83.1 | VT102 | Offline

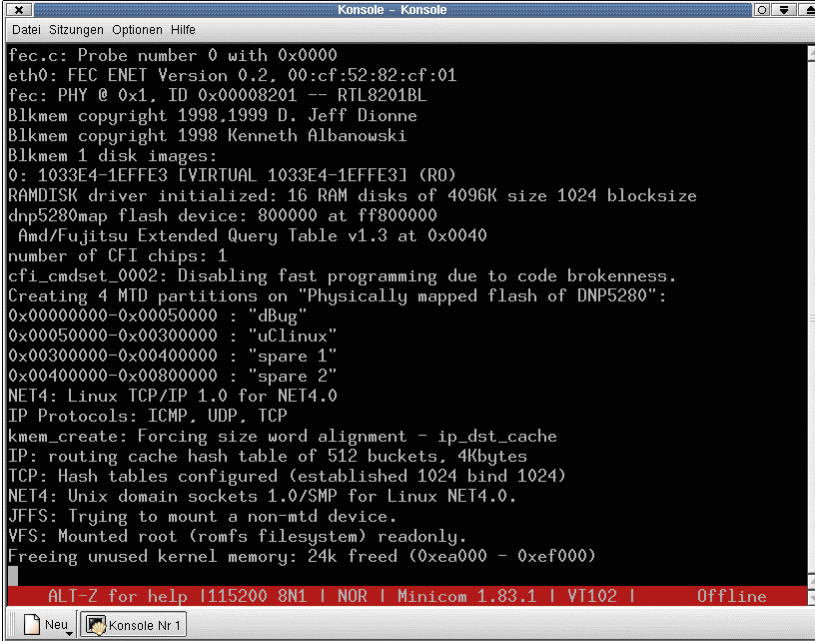
Figure 5-27: Command set with parameters

5.2.5 Running Linux

The DNP/5280 is delivered with a pre-installed Linux. When booting make sure the RCM-jumper of the DNP/5280 is not set. When the Linux boot process is done the system will stop with the login prompt shown in figure 5 30.

The DNP/5280 Linux does not need a user login with user name and password. Just enter your Linux commands directly after the boot process.

Note: On every boot process without the RCM-jumper (please see chapter 3.7) set there is a serial console available with following parameters: 115 200 bps, No Parity, 8 Data Bits, 1 Stop Bit, No Handshake.



```

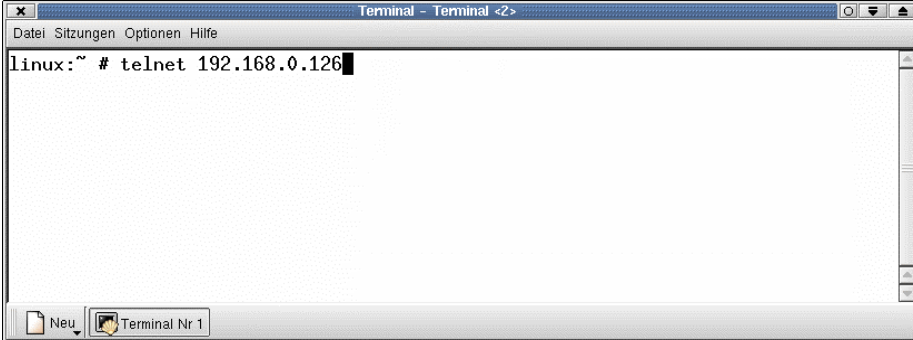
fec.c: Probe number 0 with 0x0000
eth0: FEC ENET Version 0.2, 00:cf:52:82:cf:01
fec: PHY @ 0x1, ID 0x00008201 -- RTL8201BL
Blkmem copyright 1998,1999 D. Jeff Dionne
Blkmem copyright 1998 Kenneth Albanowski
Blkmem 1 disk images:
0: 1033E4-1EFFE3 [VIRTUAL 1033E4-1EFFE3] (R0)
RAMDISK driver initialized: 16 RAM disks of 4096K size 1024 blocksize
dnp5280map flash device: 800000 at ff800000
Amd/Fujitsu Extended Query Table v1.3 at 0x0040
number of CFI chips: 1
cfi_cmdset_0002: Disabling fast programming due to code brokenness.
Creating 4 MTD partitions on "Physically mapped flash of DNP5280":
0x00000000-0x00050000 : "dBug"
0x00050000-0x00300000 : "uClinux"
0x00300000-0x00400000 : "spare 1"
0x00400000-0x00800000 : "spare 2"
NET4: Linux TCP/IP 1.0 for NET4.0
IP Protocols: ICMP, UDP, TCP
kmem_create: Forcing size word alignment - ip_dst_cache
IP: routing cache hash table of 512 buckets, 4Kbytes
TCP: Hash tables configured (established 1024 bind 1024)
NET4: Unix domain sockets 1.0/SMP for Linux NET4.0.
JFFS: Trying to mount a non-mtd device.
VFS: Mounted root (romfs filesystem) readonly.
Freeing unused kernel memory: 24k freed (0xea000 - 0xef000)

ALT-Z for help | 115200 8N1 | NOR | Minicom 1.83.1 | VT102 | Offline

```

Figure 5-28: Linux boot process

Alternatively you can use a **Command Line Interface (CLI)** like a Telnet client to communicate with the DNP/5280. Type in the command `telnet 192.168.0.126`. If you have already assigned a different IP-address to the DNP/5280 you need to enter this new IP-address in the command line.



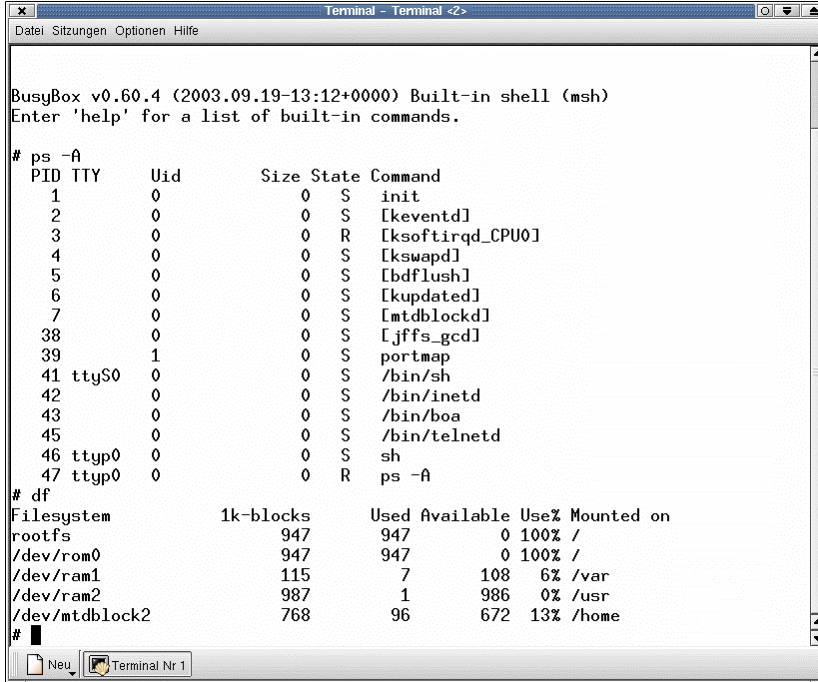
```

linux:~ # telnet 192.168.0.126

```

Figure 5-29: Linux login

Within the Telnet client you can enter Linux commands that will be executed by the DNP/5280. The standard output will be shown in your Telnet client window as illustrated in the next figure.



```
Terminal - Terminal <2>
Datei Sitzungen Optionen Hilfe

BusyBox v0.60.4 (2003.09.19-13:12+0000) Built-in shell (msh)
Enter 'help' for a list of built-in commands.

# ps -A
PID TTY      Uid        Size State Command
  1   0          0           0 S   init
  2   0          0           0 S   [keventd]
  3   0          0           0 R   [ksoftirqd_CPU0]
  4   0          0           0 S   [kswapd]
  5   0          0           0 S   [bdflush]
  6   0          0           0 S   [kupdated]
  7   0          0           0 S   [mtdblockd]
 38   0          0           0 S   [jffs_gcd]
 39   0          0           0 S   portmap
 41  ttyS0      0           0 S   /bin/sh
 42   0          0           0 S   /bin/inetd
 43   0          0           0 S   /bin/boa
 45   0          0           0 S   /bin/telnetd
 46  tty0      0           0 S   sh
 47  tty0      0           0 R   ps -A

# df
Filesystem      1k-blocks    Used Available Use% Mounted on
rootfs           947          947         0 100% /
/dev/rom0        947          947         0 100% /
/dev/ram1        115           7          108   6% /var
/dev/ram2        987           1          986   0% /usr
/dev/mtdblock2  768           96         672  13% /home

#
```

Figure 5-30: Enter Linux commands via Telnet

Note: You can enter Linux commands in different Command Line Interfaces (CLI), i.e. a serial console (like HyperTerminal or Minicom) or a Telnet client.

5.2.6 File Transfer via TFTP

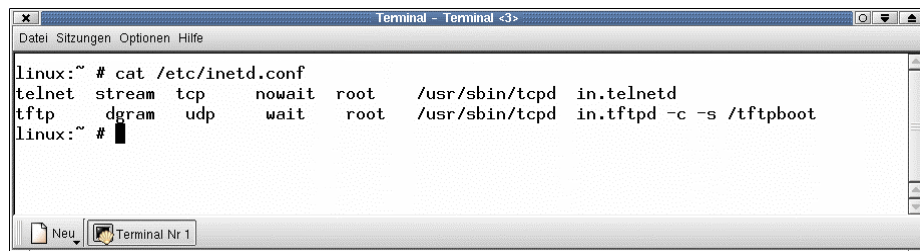
The DIL/NetPC DNP/5280 offers a very simple way for Ethernet-based file transfers between your PC system and the DNP/5280 RAM disk drives or JFFS-based flash disk drives. This file transfer is using the TCP/IP service **TFTP (Trivial File Transfer Protocol)**.

TFTP is server/client-based. The DIL/NetPC DNP/5280 Linux configuration offers a TFTP client program. Your PC needs a TFTP server program.

Set-up an Ethernet link between the DNP/5280 10/100 Mbps Ethernet interface and the Ethernet interface of your PC system. Check the IP address of the PC system with the Linux command *ifconfig*. The default IP address (factory setup) of the DNP/5280 is 192.168.0.126.

Now run a TFTP server program on your PC system. Most Linux-based PCs come with a pre-installed TFTP server program. Some of these systems start this TFTP server program at boot time (the TFTP server is a part of the *inetd* service).

In all other cases you have to edit one or more configuration files (SuSE: */etc/inetd.conf*). See the user documentation of your Linux distribution for details.



```

Terminal - Terminal <3>
Datei Sitzungen Optionen Hilfe

linux:~ # cat /etc/inetd.conf
telnet stream tcp nowait root /usr/sbin/tcpd in.telnetd
tftp dgram udp wait root /usr/sbin/tcpd in.tftpd -c -s /tftpboot
linux:~ #
  
```

Figure 5 31: Running TFTP32

Check the TFTP connection between the DIL/NetPC DNP/5280 and your PC system. Open a Telnet session and use the following commands for downloading and uploading files:

tftp -g -l file.name ip-addr

tftp -p -l file.name ip-addr

The command *tftp* is the name of the DNP/5280 TFTP client program.

The parameter *-g* stands for get (get a file from the PC system to the DNP/5280).

The parameter *-p* stands for put (put a file from the DNP/5280 to the PC system).

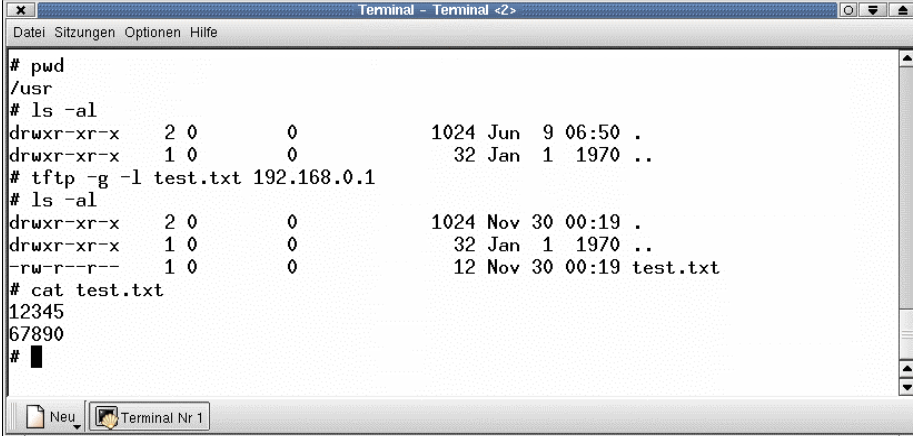
The parameter *-l file.name* specifies the file for put or get.

The parameter *ip-addr* stands for the IP address of your PC system (i.e. 192.168.0.1).

Most TFTP server programs work with a default directory for put and get commands. Each TFTP put command writes a file to this directory. Each TFTP get command reads the file from this directory on your PC system. Most TFTP server programs allow you to change this directory.

Example:

The following picture shows the use of the DNP/5280 TFTP client within a Telnet session.



```
Terminal - Terminal <2>
Datei Sitzungen Optionen Hilfe
# pwd
/usr
# ls -al
drwxr-xr-x  2 0      0          1024 Jun  9 06:50 .
drwxr-xr-x  1 0      0          32 Jan  1 1970 ..
# tftp -g -l test.txt 192.168.0.1
# ls -al
drwxr-xr-x  2 0      0          1024 Nov 30 00:19 .
drwxr-xr-x  1 0      0          32 Jan  1 1970 ..
-rw-r--r--  1 0      0          12 Nov 30 00:19 test.txt
# cat test.txt
12345
67890
# █
```

Figure 5 32: Using the DNP/5280 TFTP client within a Telnet session

Note: A file transfer to the DNP/5280 must be started with a Telnet session from RAM disk or JFFS-based flash disk directories. You need R/W access for the TFTP get command.

5.2.7 GNU Cross Tool Chain

This chapter describes how to install and use the Linux **GNU Cross Tool Chain** for DNP/5280 Linux C programming. You need administrator rights on your Linux PC for following these steps.

The GNU Cross Tool Chain for DNP/5280 Linux C programming comes within a Linux shell script file with the name *m68k-elf-tool-20030314.sh*. You find this file at the DIL/NetPC DNP/5280 Starter Kit CD-ROM. The location of this 18 Mbytes shell script file is *\uCLinux\Toolchain*.

Point your file manager to *m68k-elf-tool-20030314.sh*.

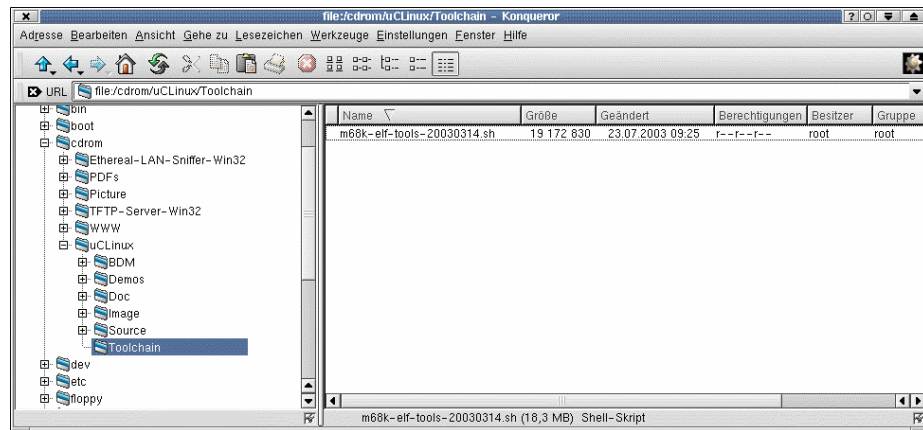


Figure 5 33: Location of *m68k-elf-tool-20030314.sh* at the DNP/5280 Starter Kit CD-ROM

Now copy *m68k-elf-tool-20030314.sh* to your local hard disk drive. Change the file attributes to executable. For this task you can use the Linux command line:

chmod +x m68k-elf-tool-20030314.sh.

Some file managers offer simpler ways for attribute changing.

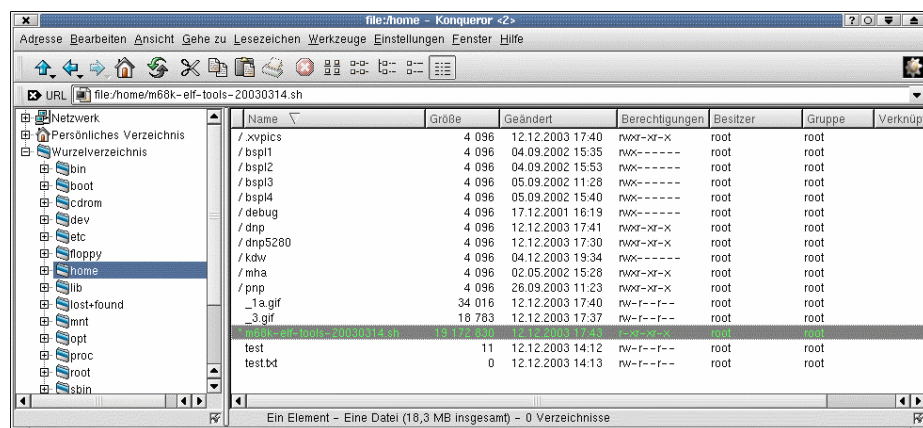
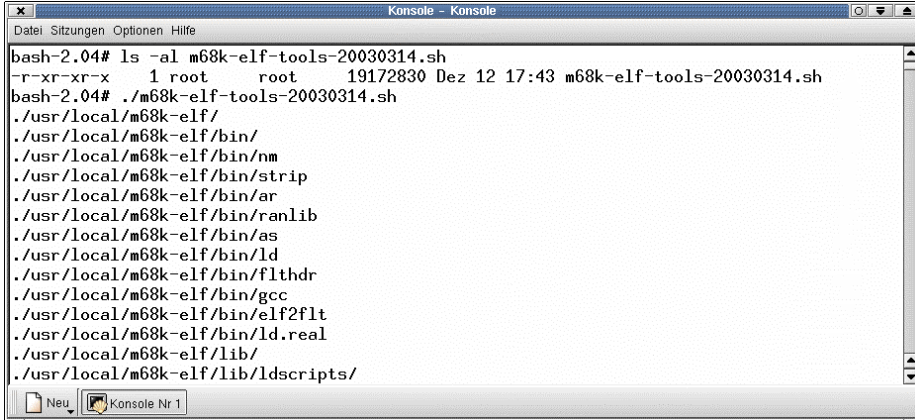


Figure 5 34: Copying *m68k-elf-tool-20030314.sh* to the local hard disk drive

Run the shell script file *m68k-elf-tool-20030314.sh* from a console window at your Linux-based PC. The shell script creates new directories at */usr/local* and copies many files to the new directory of your PC hard disk drive.



```

Könsole - Könsole
Datei Sitzungen Optionen Hilfe
bash-2.04# ls -al m68k-elf-tools-20030314.sh
-r-xr-xr-x  1 root  root  19172830 Dez 12 17:43 m68k-elf-tools-20030314.sh
bash-2.04# ./m68k-elf-tools-20030314.sh
./usr/local/m68k-elf/
./usr/local/m68k-elf/bin/
./usr/local/m68k-elf/bin/nm
./usr/local/m68k-elf/bin/strip
./usr/local/m68k-elf/bin/ar
./usr/local/m68k-elf/bin/ranlib
./usr/local/m68k-elf/bin/as
./usr/local/m68k-elf/bin/ld
./usr/local/m68k-elf/bin/flthdr
./usr/local/m68k-elf/bin/gcc
./usr/local/m68k-elf/bin/elf2flt
./usr/local/m68k-elf/bin/ld.real
./usr/local/m68k-elf/lib/
./usr/local/m68k-elf/lib/ldscripts/

```

Figure 5 35: *m68k-elf-tool-20030314.sh* creates new directories at */usr/local*

Now it is time for a test drive with the new GNU Cross Tool Chain. Open up a console window and create a new directory */home/dnp5280* for DNP/5280 Linux C programming. Then change to this directory and enter the following command lines:

```

cat > hello.c
#include <stdio.h>
#include <stdlib.h>
void main (void)

{
printf ("Hello from DNP/5280!");
}

```

C+C stops the cat command and saves the input to the file *hello.c*.

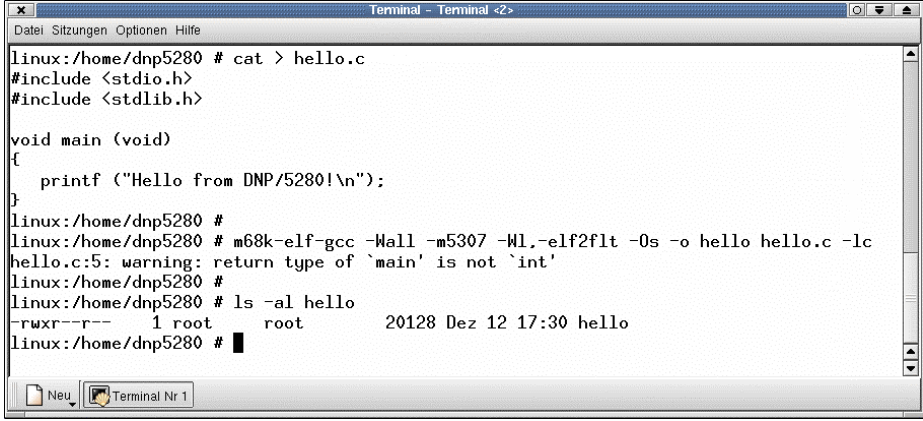
These command lines create the new file *hello.c* and put some C source code lines to this new file. The command line:

```
cat hello.c
```

displays the current content of *hello.c*. For building an executable from *hello.c* please enter the following command line:

```
m68k-elf-gcc -Wall -m5307 -Wl,-elf2flt -Os -o hello hello.c -lc
```

This command line runs the GNU C cross compiler and linker. After a successful run you will find an executable for the DNP/5280 within the same directory.

A terminal window titled "Terminal - Terminal <2>" showing the process of creating and running a C program. The user enters the following commands and receives the following output:

```
linux:/home/dnp5280 # cat > hello.c
#include <stdio.h>
#include <stdlib.h>

void main (void)
{
    printf ("Hello from DNP/5280!\n");
}
linux:/home/dnp5280 #
linux:/home/dnp5280 # m68k-elf-gcc -Wall -m5307 -Wl,-elf2flt -Os -o hello hello.c -lc
hello.c:5: warning: return type of `main' is not `int'
linux:/home/dnp5280 #
linux:/home/dnp5280 # ls -al hello
-rwxr--r--  1 root  root    20128 Dez 12 17:30 hello
linux:/home/dnp5280 #
```

Figure 5 36: Working with the GNU Cross Tool Chain

Transfer the executable from your PC hard disk drive to the DNP/5280 RAM disk or JFFS-based flash disk drive and run the executable on your DNP/5280. Use a TFTP session and a Telnet session for this task. Please enter the following commands within the DNP/5280 Telnet session window:

```
tftp -g -l hello 192.168.0.1
chmod +x hello
./hello
```

The first command line transfers the executable *hello* from the PC to the DIL/NetPC DNP/5280. This line assumes that the PC is using the IP address 192.168.0.1. The second line makes sure that the executable attribute is set for *hello*. The next command line runs *hello*.

5.2.8 GNU Cross Debugger

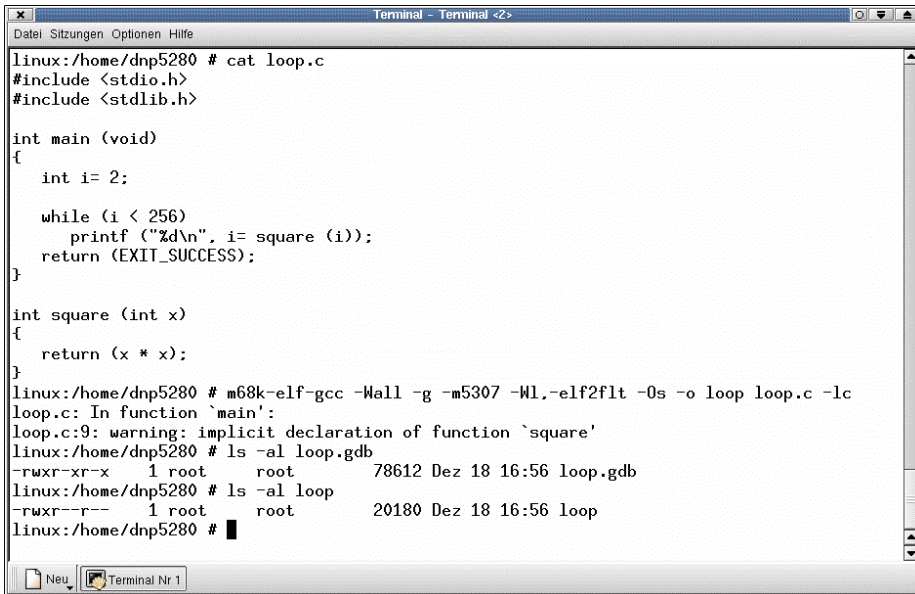
The GNU Cross Tool Chain for DNP/5280 Linux C programming offers a pre-build cross version of the **GNU Debugger**, called *m68k-elf-gdb*.

This debugger runs on a Linux-based PC and allows you to debug DNP/5280 μ CLinux executables with ELF layout at C source code level over a remote connection to the DNP/5280.

The cross debugger needs an Ethernet-based TCP/IP link between the PC and the DNP/5280. In addition the debugger needs also a remote debugging agent, called **gdbserver** for the DNP/5280. This agent is pre-installed within the DNP/5280 Linux.

Write your C program and translate the C source code with the GNU cross C compiler to an executable and a symbol file. Use the following command line with the **-g** parameter. This sample command line builds an executable, called *loop* from a source code file with the name *loop.c* and a file *loop.gdb* with symbol information:

```
m68k-elf-gcc -Wall -g -m5307 -Wl,-elf2flt -Os -o loop loop.c -lc
```



```

linux:/home/dnp5280 # cat loop.c
#include <stdio.h>
#include <stdlib.h>

int main (void)
{
    int i= 2;

    while (i < 256)
        printf ("%d\n", i= square (i));
    return (EXIT_SUCCESS);
}

int square (int x)
{
    return (x * x);
}
linux:/home/dnp5280 # m68k-elf-gcc -Wall -g -m5307 -Wl,-elf2flt -Os -o loop loop.c -lc
loop.c: In function `main':
loop.c:9: warning: implicit declaration of function `square'
linux:/home/dnp5280 # ls -al loop.gdb
-rwxr-xr-x  1 root  root    78612 Dez 18 16:56 loop.gdb
linux:/home/dnp5280 # ls -al loop
-rwxr--r--  1 root  root    20180 Dez 18 16:56 loop
linux:/home/dnp5280 #

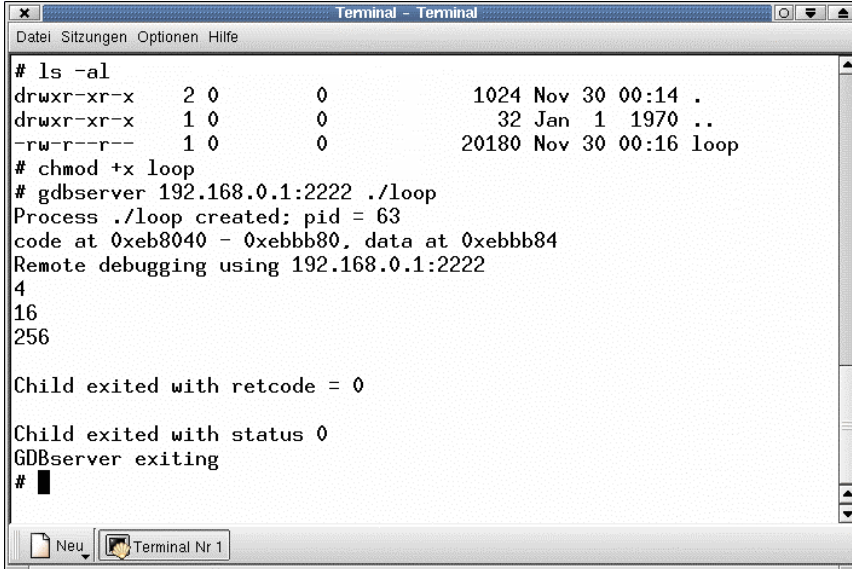
```

Figure 5 37: Compiling a C program with the GNU Cross Debugger

Transfer the executable from your PC hard disk drive to the DNP/5280 RAM disk or JFFS-based flash disk drive and run the executable on your DNP/5280 with the help of *gdbserver*. Use a TFTP session and a Telnet session for this task. Please enter the following command lines within the DNP/5280 Telnet session window:

```
tftp -g -l loop 192.168.0.1
chmod +x loop
gdbserver 192.168.0.1:2222 ./loop
```

The first command line transfers the executable *loop* from the PC to the DIL/NetPC DNP/5280. This line assumes that your PC is using the IP address 192.168.0.1. The second line makes sure that the executable attribute is set for *hello*. The third command line runs *loop* with the help of *gdbserver*. Within this command line you need the IP address of the PC together with a TCP/IP port number. We use the port number 2222 for this sample.



```

Terminal - Terminal
Datei Sitzungen Optionen Hilfe

# ls -al
drwxr-xr-x  2 0      0          1024 Nov 30 00:14 .
drwxr-xr-x  1 0      0          32 Jan  1 1970 ..
-rw-r--r--  1 0      0          20180 Nov 30 00:16 loop
# chmod +x loop
# gdbserver 192.168.0.1:2222 ./loop
Process ./loop created: pid = 63
code at 0xeb8040 - 0xebbb80, data at 0xebbb84
Remote debugging using 192.168.0.1:2222
4
16
256

Child exited with retcode = 0

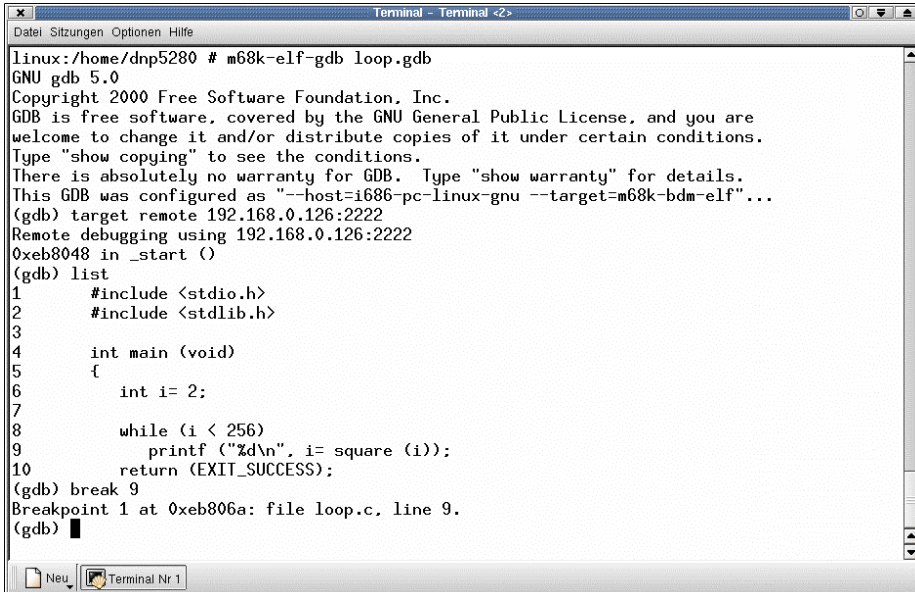
Child exited with status 0
GDBserver exiting
# █

```

Figure 5 38: File transfer and execution

Run the GNU Cross Debugger *m68k-elf-gdb* on your PC. Use the following command line. The parameter *loop.gdb* is the file name for the symbol information file.

m68k-elf-gdb loop.gdb



```

Terminal - Terminal <2>
Datei Sitzungen Optionen Hilfe

linux:/home/dnp5280 # m68k-elf-gdb loop.gdb
GNU gdb 5.0
Copyright 2000 Free Software Foundation, Inc.
GDB is free software, covered by the GNU General Public License, and you are
welcome to change it and/or distribute copies of it under certain conditions.
Type "show copying" to see the conditions.
There is absolutely no warranty for GDB. Type "show warranty" for details.
This GDB was configured as "--host=i686-pc-linux-gnu --target=m68k-bdm-elf"...
(gdb) target remote 192.168.0.126:2222
Remote debugging using 192.168.0.126:2222
0xeb8048 in _start ()
(gdb) list
1      #include <stdio.h>
2      #include <stdlib.h>
3
4      int main (void)
5      {
6          int i= 2;
7
8          while (i < 256)
9              printf ("%d\n", i= square (i));
10         return (EXIT_SUCCESS);
(gdb) break 9
Breakpoint 1 at 0xeb806a: file loop.c, line 9.
(gdb) █

```

Figure 5 39: The GNU Cross Debugger at work

Now the debugger waits for your debugging commands. First please enter always the following command line:

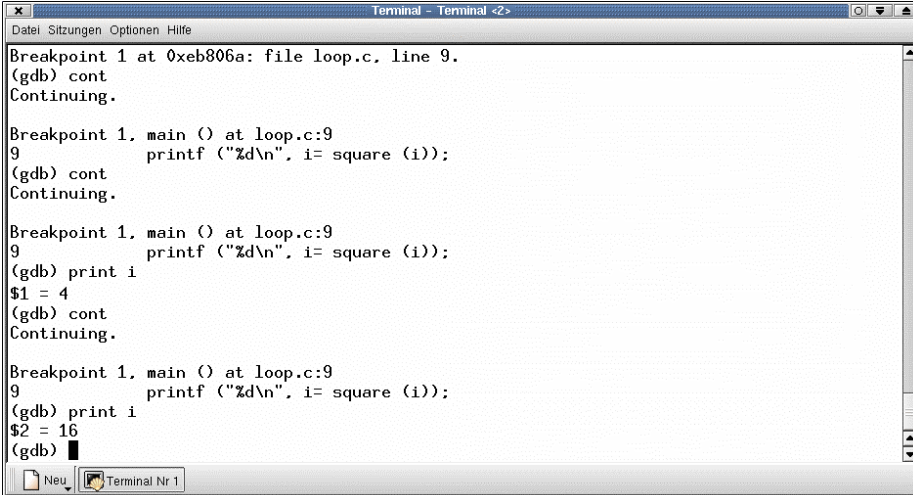
```
target remote 192.168.0.126:2222
```

This debugger command line sets up the Ethernet-based TCP/IP connection between the PC and the DNP/5280.

Please use the same TCP/IP port number (2222). The sample command line assumes that the DNP/5280 uses the IP address 192.168.0.126.

Then set your breakpoints within the C source code and run your program with the remote debugging session between the PC and the DNP/5280.

Use the debugger command *continue* for running the program. The program runs to the next breakpoint. The short form for this command is *cont*.



```
Breakpoint 1 at 0xeb806a: file loop.c, line 9.
(gdb) cont
Continuing.

Breakpoint 1, main () at loop.c:9
9      printf ("%d\n", i= square (i));
(gdb) cont
Continuing.

Breakpoint 1, main () at loop.c:9
9      printf ("%d\n", i= square (i));
(gdb) print i
$1 = 4
(gdb) cont
Continuing.

Breakpoint 1, main () at loop.c:9
9      printf ("%d\n", i= square (i));
(gdb) print i
$2 = 16
(gdb)
```

Figure 5 40: Setting breakpoints

5.2.9 GNU Cross Debugger with DDD (Data Display Debugger)

The GNU Cross Tool Chain for DNP/5280 Linux C programming offers a pre-build cross version of the GNU Debugger, called *m68k-elf-gdb*. This debugger runs on a Linux-based PC and allows you to debug DNP/5280 μ CLinux executables with ELF layout at C source code level over a remote connection to the DNP/5280.

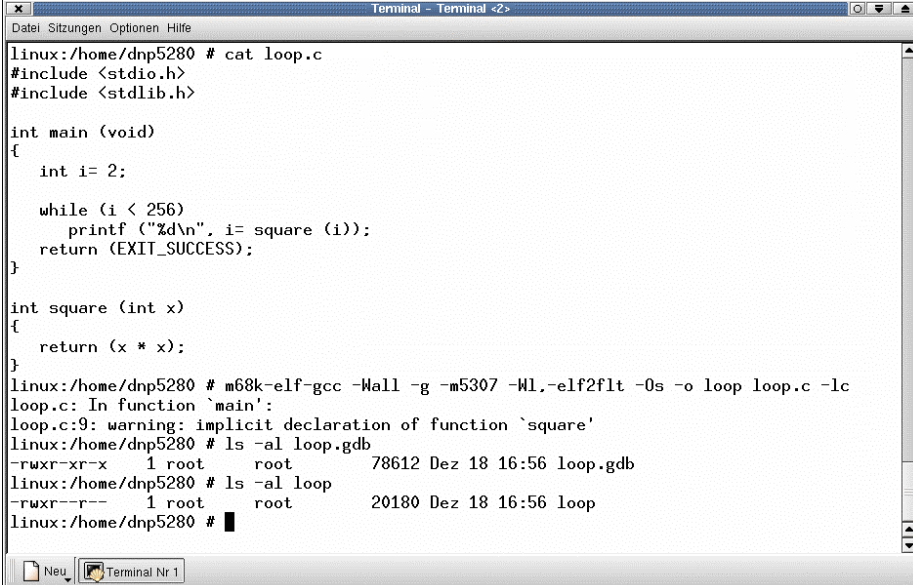
The cross debugger needs an Ethernet-based TCP/IP link between the PC and the DNP/5280. In addition the debugger needs also a remote debugging agent, called *gdbserver* for the DNP/5280. This agent is pre-installed within the DNP/5280 Linux.

The GNU debugger offers a simple command line interface and a lot of different commands. With the help of **DDD (Data Display Debugger** - a graphical front-end for command line debuggers) you get a powerful graphical user interface for the GNU debugger. DDD is a part of many PC Linux distributions.

DDD is also available from <http://www.gnu.org/software/ddd/>.

Write your C program and translate the C source code with the GNU cross C compiler to an executable and a symbol file. Use the following command line with the *-g* parameter. This sample command line builds an executable, called *loop* from a source code file with the name *loop.c* and a file *loop.gdb* with symbol information.

```
m68k-elf-gcc -Wall -g -m5307 -Wl,-elf2flt -Os -o loop loop.c -lc
```



```

linux:/home/dnp5280 # cat loop.c
#include <stdio.h>
#include <stdlib.h>

int main (void)
{
    int i= 2;

    while (i < 256)
        printf ("%d\n", i= square (i));
    return (EXIT_SUCCESS);
}

int square (int x)
{
    return (x * x);
}

linux:/home/dnp5280 # m68k-elf-gcc -Wall -g -m5307 -Wl,-elf2flt -Os -o loop loop.c -lc
loop.c: In function `main':
loop.c:9: warning: implicit declaration of function `square'
linux:/home/dnp5280 # ls -al loop.gdb
-rwxr-xr-x  1 root  root    78612 Dez 18 16:56 loop.gdb
linux:/home/dnp5280 # ls -al loop
-rwxr--r--  1 root  root    20180 Dez 18 16:56 loop
linux:/home/dnp5280 #

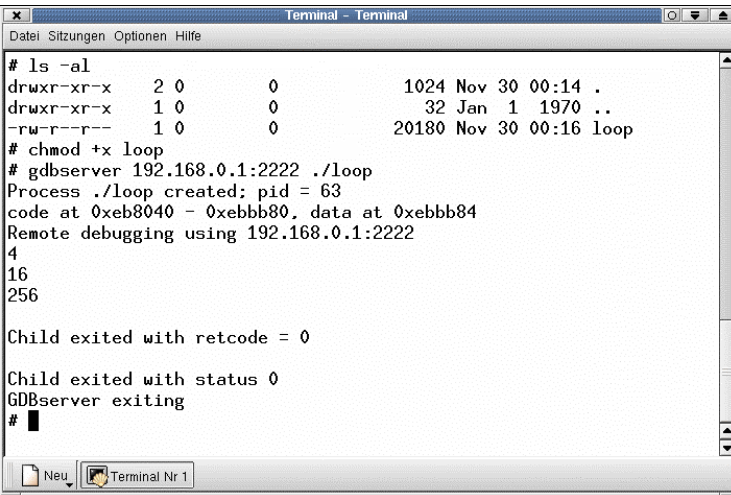
```

Figure 5 41: Compiling a C program

Then transfer the executable from your PC hard disk drive to the DNP/5280 RAM disk or JFFS-based flash disk drive and run the executable on your DNP/5280 with the help of *gdbserver*. Use a TFTP session and a Telnet session for this task. Please enter the commands on the next page within the DNP/5280 Telnet session window:

```
tftp -g -l loop 192.168.0.1
chmod +x loop
gdbserver 192.168.0.1:2222 ./loop
```

The first command line transfers the executable *loop* from the PC to the DIL/NetPC DNP/5280. This line assumes that your PC uses the IP address 192.168.0.1. The second line makes sure that the executable attribute is set for *hello*. The third command line runs *loop* with the help of *gdbserver*. Within this command line you need the IP address of the PC together with a TCP/IP port number. We use the port number 2222 for this sample.



```
Terminal - Terminal
Datei Sitzungen Optionen Hilfe
# ls -al
drwxr-xr-x  2 0      0          1024 Nov 30 00:14 .
drwxr-xr-x  1 0      0          32 Jan  1 1970 ..
-rw-r--r--  1 0      0          20180 Nov 30 00:16 loop
# chmod +x loop
# gdbserver 192.168.0.1:2222 ./loop
Process ./loop created; pid = 63
code at 0xeb8040 - 0xebb80, data at 0xebbb84
Remote debugging using 192.168.0.1:2222
4
16
256

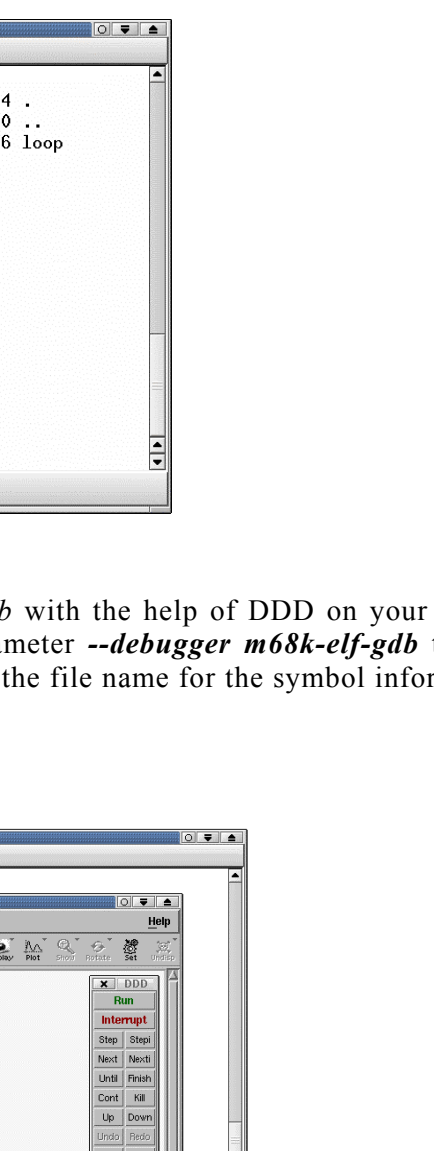
Child exited with retcode = 0

Child exited with status 0
GDBserver exiting
# █
```

Figure 5 42: File transfer and execution

Run the GNU Cross Debugger *m68k-elf-gdb* with the help of DDD on your PC. Use the following command line. The parameter *--debugger m68k-elf-gdb* tells DDD the name of the debugger, *loop.gdb* is the file name for the symbol information file.

```
ddd --debugger m68k-elf-gdb loop.gdb
```



```
Terminal - Terminal
Datei Sitzungen Optionen Hilfe
linux:/home/dnp5280 # ddd --debugger m68k-elf-gdb loop.gdb

DDD: /home/dnp5280/loop.c
File Edit View Program Commands Status Source Data Help
(): main
#include <stdio.h>
#include <stdlib.h>

int main (void)
{
  int i = 2;

  while (i < 256)
    printf ("%d\n", i = square (i));
  return (EXIT_SUCCESS);
}

int square (int x)
{
  return (x * x);
}

GNU DDD 3.2.1 (i386-suse-linux), by Dorothea Lütkehaus and Andreas Zeller.
Copyright © 1995-1999 Technische Universität Braunschweig, Germany.
Copyright © 1999-2000 Universität Passau, Germany.
(gdb) █

Welcome to DDD 3.2.1 "LiftOff" (i386-suse-linux)
```

Figure 5 43: Working with the DDD

Now the debugger waits for your debugging commands. First please enter always the following command line within the DDD command line window:

target remote 192.168.0.126:2222

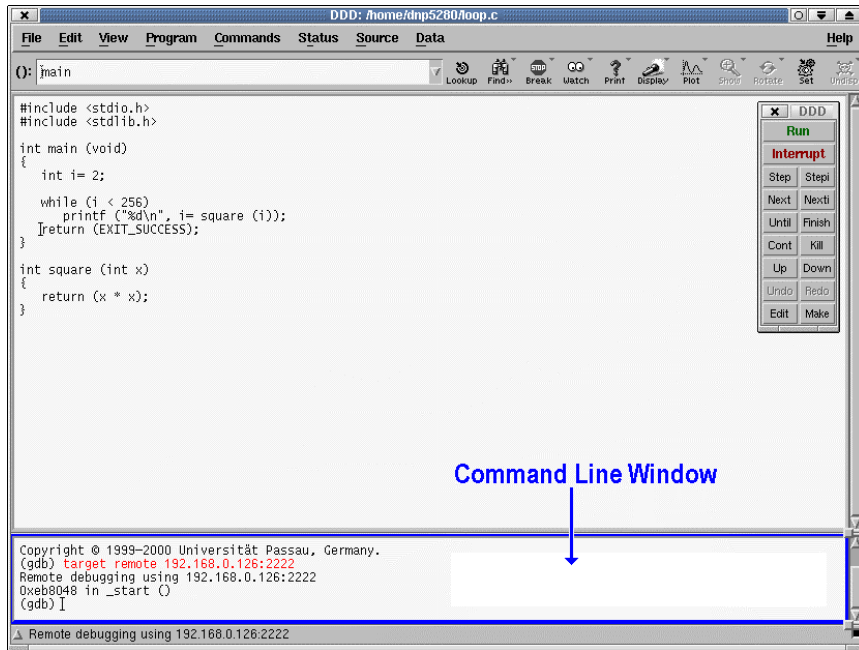


Figure 5 44: Typing commands in the command line window

This debugger command line sets up the Ethernet-based TCP/IP connection between the PC and the DNP/5280. Please use the same TCP/IP port number (2222). The sample command line assumes that the DNP/5280 uses the IP address 192.168.0.126.

Then set your breakpoints within the C source code and run your program with your remote debugging session between the PC and the DNP/5280.

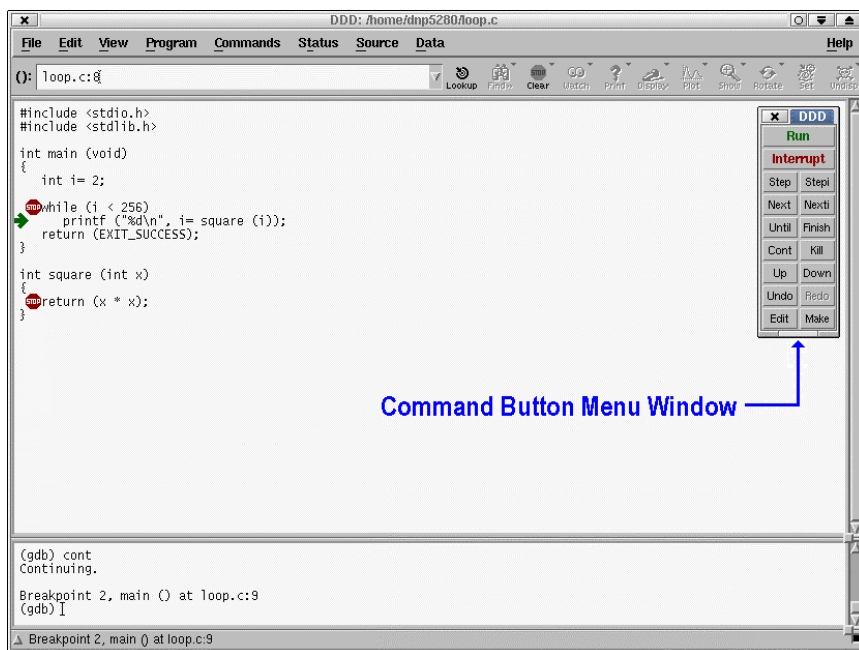


Figure 5 45: Using the command button menu window

DDD allows you to set breakpoints with your mouse. Just put the mouse cursor over the source code line of your choice and press the right hand mouse button. Then use the command button for

continue

from the command button menu window for running the program. The program runs to the next (or first) breakpoint. You can also use the command button

step

for single-stepping at C language level through your program. If the program execution stops, you can enter debugger commands within the DDD command line window. For example

show version

The GNU Debugger shows then some copyright and version information and the current configuration (Build for Host *i686-pc-linux-gnu*. Build for Target *m68k-bdm-elf*).

6 Appendix

Appendix 1: The DNP/5280 in Detail

A1.1 Block Diagram

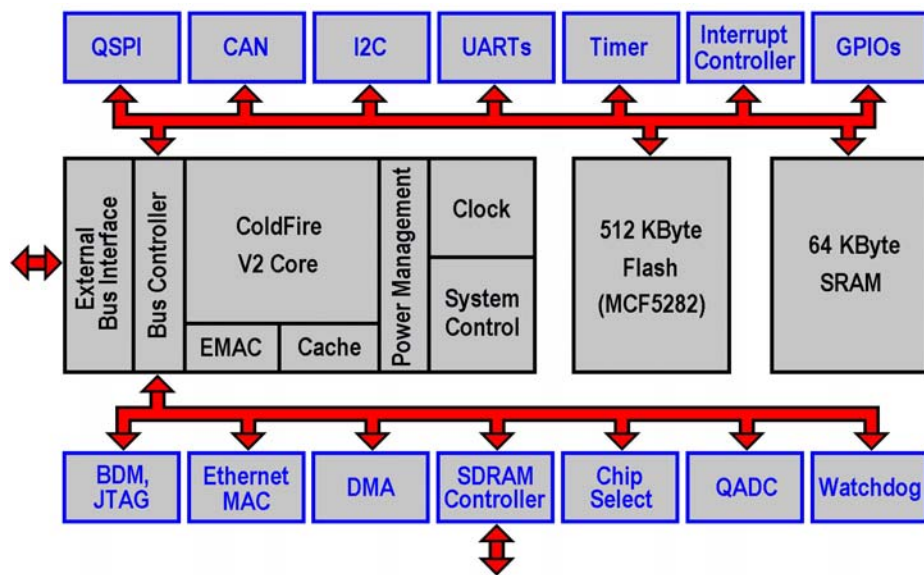


Figure A1-1: Block Diagram of the MCF5280/MCF5282-Microcontroller

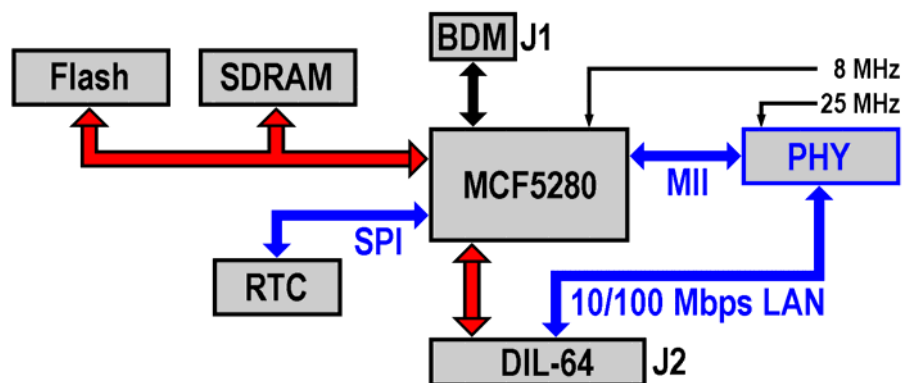


Figure A1-2: Block Diagram of the DNP/5280

A1.2 Pin Assignment – 64-pin DIL Connector (1. Part)

Pin	Name	Group	Function
1	PA0	PIO	Parallel I/O, Port A, Bit 0
2	PA1	PIO	Parallel I/O, Port A, Bit 1
3	PA2	PIO	Parallel I/O, Port A, Bit 2
4	PA3	PIO	Parallel I/O, Port A, Bit 3
5	PA4	PIO	Parallel I/O, Port A, Bit 4
6	PA5	PIO	Parallel I/O, Port A, Bit 5
7	PA6	PIO	Parallel I/O, Port A, Bit 6
8	PA7	PIO	Parallel I/O, Port A, Bit 7
9	PB0	PIO	Parallel I/O, Port B, Bit 0
10	PB1	PIO	Parallel I/O, Port B, Bit 1
11	PB2	PIO	Parallel I/O, Port B, Bit 2
12	PB3	PIO	Parallel I/O, Port B, Bit 3
13	PB4	PIO	Parallel I/O, Port B, Bit 4
14	PB5	PIO	Parallel I/O, Port B, Bit 5
15	PB6	PIO	Parallel I/O, Port B, Bit 6
16	PB7	PIO	Parallel I/O, Port B, Bit 7
17	PC0	PIO	Parallel I/O, Port C, Bit 0
18	PC1	PIO	Parallel I/O, Port C, Bit 1
19	PC2	PIO	Parallel I/O, Port C, Bit 2
20	PC3	PIO	Parallel I/O, Port C, Bit 3
21	RXD1	SIO	COM1 Serial Port, RXD Pin
22	TXD1	SIO	COM1 Serial Port, TXD Pin
23	CTS1	SIO	COM1 Serial Port, CTS Pin
24	RTS1	SIO	COM1 Serial Port, RTS Pin
25	DCD1	SIO	COM1 Serial Port, DCD Pin
26	DSR1	SIO	COM1 Serial Port, DSR Pin
27	DTR1	SIO	COM1 Serial Port, DTR Pin
28	RI1	SIO	COM1 Serial Port, RI Pin
29	RESIN	RESET	Reset Input
30	TX+	LAN	10/100 Mbps LAN, TX+ Pin
31	TX-	LAN	10/100 Mbps LAN, TX- Pin
32	GND	----	Ground

Table A1-1: DNP/5280 Pinout – Pin 1 to 32

A1.3 Pin Assignment – 64-pin DIL Connector (2. Part)

Pin	Name	Group	Function
33	RX+	LAN	10/100 Mbps LAN, RX+ Pin
34	RX-	LAN	10/100 Mbps LAN, RX- Pin
35	RESOUT	RESET	Reset Output
36	VBAT	PSP	Real-Time Clock Battery
37	CLKOUT	PSP	Clock Output
38	TXD2	PSP	COM2 Serial Port, TXD Pin
39	RXD2	PSP	COM2 Serial Port, RXD Pin
40	INT5	PSP	Interrupt Input 5
41	INT4	PSP	Interrupt Input 4
42	INT3	PSP	Interrupt Input 3
43	INT2	PSP	Interrupt Input 2
44	INT1	PSP	Interrupt Input 1
45	CS4	PSP	Chip Select Output 4
46	CS3	PSP	Chip Select Output 3
47	CS2	PSP	Chip Select Output 2
48	CS1	PSP	Chip Select Output 1
49	IOCHRDY	PSP	I/O Channel Ready
50	IOR	PSP	I/O Read Signal
51	IOW	PSP	I/O Write Signal
52	SA3	PSP	Address Bit 3
53	SA2	PSP	Address Bit 2
54	SA1	PSP	Address Bit 1
55	SA0	PSP	Address Bit 0
56	SD7	PSP	Data Bit 7
57	SD6	PSP	Data Bit 6
58	SD5	PSP	Data Bit 5
59	SD4	PSP	Data Bit 4
60	SD3	PSP	Data Bit 3
61	SD2	PSP	Data Bit 2
62	SD1	PSP	Data Bit 1
63	SD0	PSP	Data Bit 0
64	VCC	PSP	3.3 Volt Power Input

Table A1-2: DNP/5280 Pinout – Pin 33 to 64

A1.4 DNP/5280 Function Multiplexing with 64-pin DIL Connector

Some pins of the 64-pin DIL connector of the DNP/5280 have multiple meanings. The pins have a primary and a secondary function (Function Multiplexing). The primary functions correspond with the standard pinout of the 64-pin DIL connector as shown in table 8-1 and 8-2. The secondary functions are shown in table 8-3 below.

Pin	Name	Primary functions	Secondary functions
13	PB4	Parallel I/O, Port B, Bit 4	SCL (I2C)
14	PB5	Parallel I/O, Port B, Bit 5	SDA (I2C)
15	PB6	Parallel I/O, Port B, Bit 6	CANTX (CAN)
16	PB7	Parallel I/O, Port B, Bit 7	CANRX (CAN)
17	PC0	Parallel I/O, Port C, Bit 0	QSPIDO (SPI)
18	PC1	Parallel I/O, Port C, Bit 1	QSPIDI (SPI)
19	PC2	Parallel I/O, Port C, Bit 2	QSPICLK (SPI)
20	PC3	Parallel I/O, Port C, Bit 3	QSPICS0 (SPI)

Table A1-3: DNP/5280 Function Multiplexing

A1.5 DNP/5280 LEDs

Four miniature LEDs are placed on the DNP/5280 for a visual check of the LAN activity.

Name	Function	Description
LED0	Link	Ethernet cable plugged in
LED1	Duplex	Duplex-Mode
LED2	10Act	Data transmission with 10 Mbps
LED3	100Act	Data transmission with 100 Mbps

Table A1-4: DNP/5280 LEDs

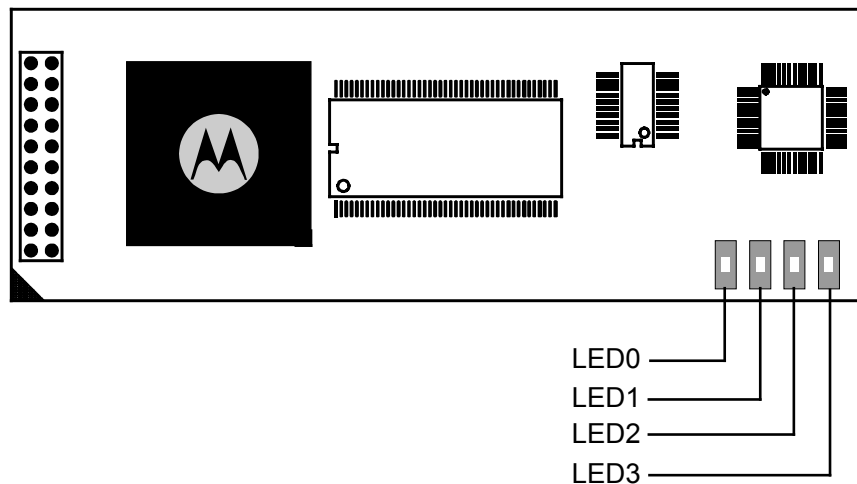


Figure A1-3: DNP/5280 LEDs

A1.6 BDM-Interface

Pin	Name	Annotation
1	VIO (3.3 VDC I/O Voltage)	
2	GND	
3	TA#	BDM-Function
4	BKPT#	BDM-Function
5	Reset#	BDM-Function
6	DSCLK#	BDM-Function
7	DSI#	BDM-Function
8	TCLK	BDM-Function
9	PST3	BDM-Function
10	DS0	BDM-Function
11	PST2	BDM-Function
12	DDATA3	BDM-Function
13	PST1	BDM-Function
14	DDATA2	BDM-Function
15	PST0	BDM-Function
16	DDATA1	BDM-Function
17	PSTCLK	BDM-Function
18	DDATA0	BDM-Function
19	GND	
20	RCM	GPTB3

Table A1-5: DNP/5280 BDM-Interface

Pin 19 – Pin 20	Effects
Jumper not set	GPTB3 = 1 (High)
Jumper set	GPTB3 = 0 (Low)

Table A1-6: DNP/5280 RCM-Jumper

A1.7 PIO-Mapping

The 20 Signals for the DNP/5280-Parallel-I/O (PIO) are realized through different function units of the MCF5280. The following table shows the assignment. Pin names for the MCF5280-case (256 MAPBGA) are listed in the third column. Please see the MCF5282 ColdFire Microcontroller User's Manual R.0.1 (MCF5282UM/D) for further details.

Pin	Name	MCF5280-Pinfunction	MCF5280-Pin
1	PA0	AN52	R4
2	PA1	AN53	T4
3	PA2	AN55	P3
4	PA3	AN56	R3
5	PA4	AN0	T3
6	PA5	AN1	R2
7	PA6	AN2	T2
8	PA7	AN3	R1
9	PB0	GPTA0	N13
10	PB1	GPTA1	P13
11	PB2	GPTA2	R13
12	PB3	GPTA3	T13
13	PB4	SCL	E15
14	PB5	SDA	E14
15	PB6	CANTX	E13
16	PB7	CANRX	D16
17	PC0	QSPIDO	F13
18	PC1	QSPIDI	E16
19	PC2	QSPICLK	F14
20	PC3	QSPICS0	F15

Table A1-7: DNP/5280 PIO-Mapping

A1.8 DNP/5280 Expansion Bus Mapping

Pin	Name	Function	MCF5280 Signal	MCF5280 Pin	Remarks
40	INT5	Interrupt Input 5	IRQ7	B15	-
41	INT4	Interrupt Input 4	IRQ6	B16	-
42	INT3	Interrupt Input 3	IRQ5	C14	-
43	INT2	Interrupt Input 2	IRQ4	C15	-
44	INT1	Interrupt Input 1	IRQ3	C16	-
45	CS4	Chip Select Output 4	RAS1#	H13	See Device Errata
46	CS3	Chip Select Output 3	CS3#	L16	-
47	CS2	Chip Select Output 2	CS2#	L15	-
48	CS1	Chip Select Output 1	CS1#	L14	-
49	RDY	External Ready Input	TA#	P16	-
50	RD	Read Signal	OE#	N16	Also on-board use
51	WR	Write Signal	R/W#	N15	Also on-board use
52	SA3	Address Bit 3	A3	E3	Also on-board use
53	SA2	Address Bit 2	A2	E4	Also on-board use
54	SA1	Address Bit 1	A1	F1	Also on-board use
55	SA0	Address Bit 0	A0	F2	Also on-board use
56	SD7	Data Bit 7	D31	F3	Also on-board use
57	SD6	Data Bit 6	D30	G1	Also on-board use
58	SD5	Data Bit 5	D29	G2	Also on-board use
59	SD4	Data Bit 4	D28	G3	Also on-board use
60	SD3	Data Bit 3	D27	G4	Also on-board use
61	SD2	Data Bit 2	D26	H1	Also on-board use
62	SD1	Data Bit 1	D25	H2	Also on-board use
63	SD0	Data Bit 0	D24	H3	Also on-board use

Table A1-8: DNP/5280 Expansion Bus Mapping

A1.9 DNP/5280 Memory Mapping

Function Unit	Startaddress	Endaddress	Access Format
SDRAM	0x0000.0000	0x00FF.FFFF	32 Bits
SRAM (intern)	0x2000.0000	0x2000.FFFF	32 Bits
CS1_Space	0x1000.0000	0x100F.FFFF	8 Bits
CS2_Space	0x1010.0000	0x101F.FFFF	8 Bits
CS3_Space	0x1020.0000	0x102F.FFFF	8 Bits
CS4_Space	0x1030.0000	0x103F.FFFF	8 Bits
IBSBAR	0x4000.0000	0x7FFF.FFFF	32 Bits
Flash (MCF5282 intern)	0xF000.0000	0xF007.FFFF	32 Bits
Flash	0xFF80.0000	0xFFFF.FFFF	16 Bits

Table A1-9: DNP/5280 Memory Mapping

The memory areas with names **CS1_Space** to **CS4_Space** are each assigned to the corresponding Chip Select Signals (CS1: Chip Select Output 1 to CS4: Chip Select Output 4) on the 64-pin DIL Connector.

In memory area **IBSBAR** the SFRs (Special Function Register) of the Motorola ColdFire MCF5280-Microcontroller are addressable.

User programs can only be loaded from 0x0001:0000 into the memory.

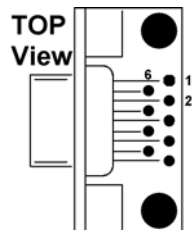
The DNP/5280 comes with a ROM-Monitor ex works. This ROM-Monitor needs a memory area in Flash and SDRAM each.

Function Unit	Startaddress	Endaddress
dBUG ROM-Monitor Code-Area	0xFF80.0000	0xFF83.FFFF
dBUG ROM-Monitor Data-Area	0x0000.0000	0x0000.FFFF

Table A1-10: DNP/5280 Reserved Areas for the ROM-Monitor

Appendix 2: Pin Assignment DNP/EVA2-SV6 Components

A2.1 COM1 Connector



Pin	Signal
1	DCD
2	RxD
3	TxD
4	DTR
5	GND

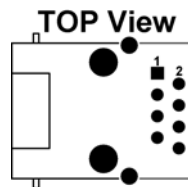
Pin	Signal
6	DSR
7	RTS
8	CTS
9	RI

Table A2-1: Pinout COM1 Connector

Caution:

All COM1-port signals are on RS232 level. There is no TTL level available on these ports. The RS232 level shifter is part of the DNP/EVA2-SV6 board!

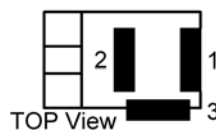
A2.2 10/100 Mbps Ethernet Connector



Pin	Name	Signal
1	TX+	TXD+
2	TX-	TXD-
3	RX+	RXD+
4	nc	---
5	nc	---
6	RX-	RXD-
7	nc	---
8	nc	---
S1...S2	Shield	---

Table A2-2: Pinout 10/100 Mbps Ethernet Connector

A2.3 Power Connector



Pin	Name	Signal
1	Vcc	Power In
2	GND	Power
3	GND	Power

Table A2-3: Pinout Power Connector

Appendix 3: Connecting an external battery to the DNP/5280

To ensure the RTC (Real Time Clock) function of the DNP/5280 when the main power is removed a backup battery must be connected between VBAT (Pin 36) and GND. This backup battery should be a lithium battery with a voltage of approx. 3VDC. If main power is turned on – no battery power will be consumed.

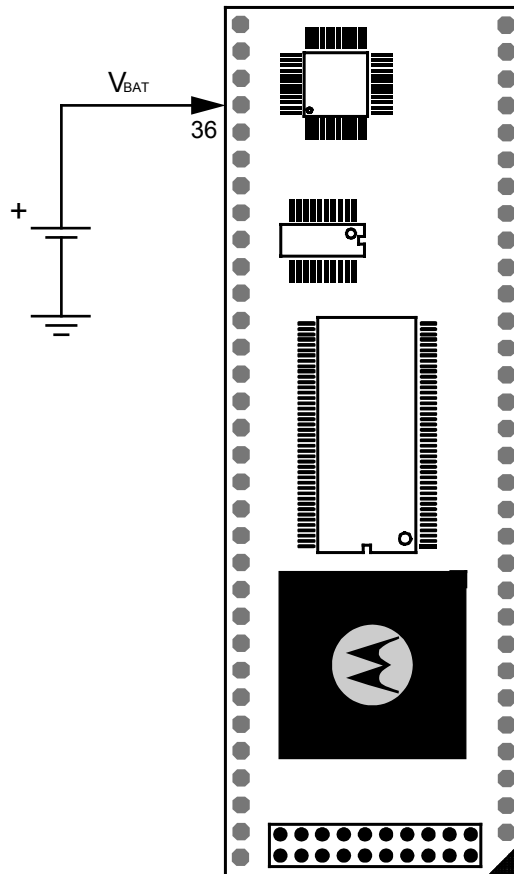


Figure A3-1: Connecting an external battery to Pin 36 of the DNP/5280

Appendix 4: Mechanical Dimensions

The DNP/5280 uses a 64-pin DIL socket as mechanical base. Figure A4-1 shows the dimensions. All length dimensions have a tolerance of 0.5 mm.

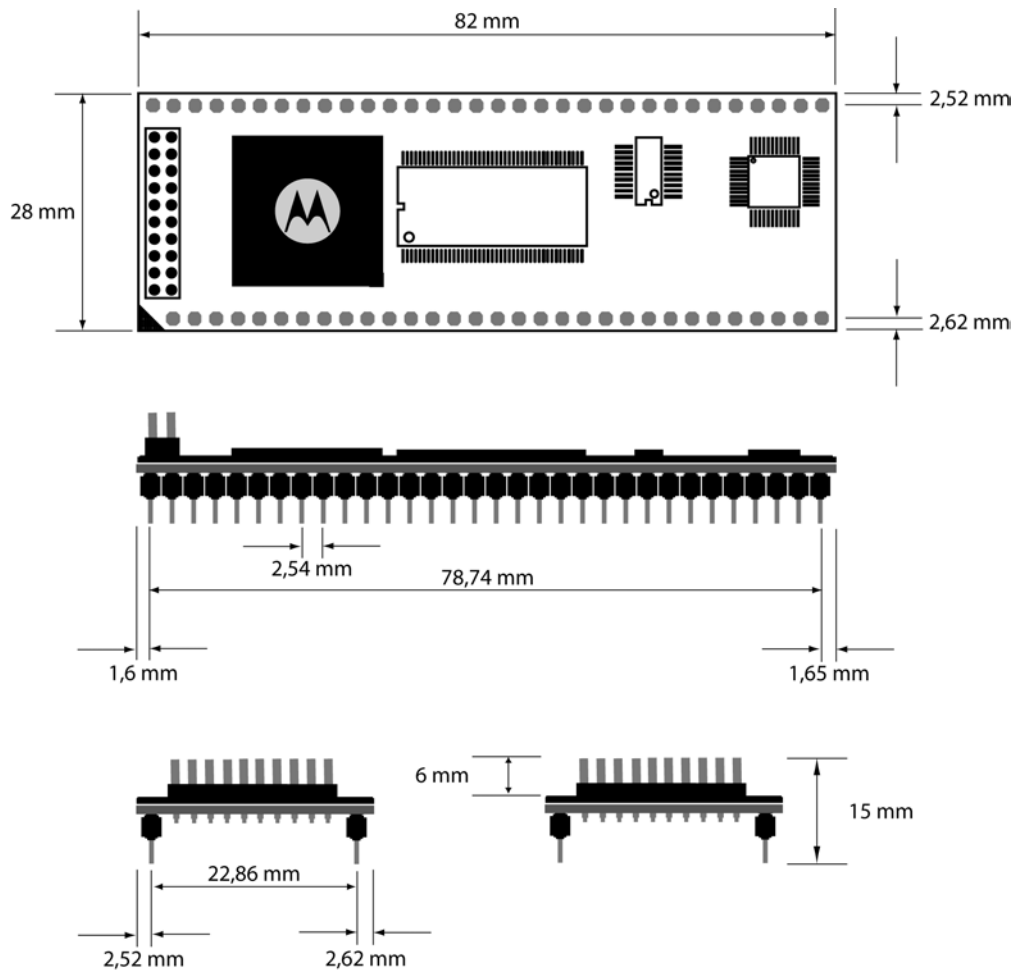


Figure A4-1: Dimensions of the DNP/5280

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